


# EUCHNER

## Operating Instructions

Non-Contact Safety Switch  
**CES-AP-C01-... (Unicode/Multicode)**

EN

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## 1. About this document

### 1.1. Scope





These operating instructions are valid for all CES-AP-C01-... of version V2.0.X. These operating instructions, the document *Safety information* and any enclosed data sheet form the complete user information for your device.

	<b>Important!</b>  Make sure to use the operating instructions valid for your product version. Please contact the EUCHNER service team if you have any questions.
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### 1.2. Target group





Design engineers and installation planners for safety systems on machines, as well as setup and servicing staff possessing special expertise in handling safety components.


### 1.3. Key to symbols

Symbol/depiction	Meaning
	Printed document
	Document is available for download at <a href="http://www.euchner.com">www.euchner.com</a>
 <b>DANGER</b> <b>WARNING</b> <b>CAUTION</b>	Safety precautions <b>Danger</b> of death or severe injuries <b>Warning</b> about possible injuries <b>Caution</b> slight injuries possible
 <b>NOTICE</b> <b>Important!</b>	<b>Notice</b> about possible device damage <b>Important</b> information
<b>Tip</b>	Useful information

### 1.4. Supplementary documents

The overall documentation for this device consists of the following documents:

Document title (document number)	Contents	
Safety information (2525460)	Basic safety information	
Operating instructions (2112663)	(this document)	
Declaration of conformity	Declaration of conformity	
Possibly enclosed data sheet	Item-specific information about deviations or additions	

	<b>Important!</b>  Always read all documents to gain a complete overview of safe installation, setup and use of the device. The documents can be downloaded from <a href="http://www.euchner.com">www.euchner.com</a> . Simply enter the document number or the order number in the search box.
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## 2. Correct use

Safety switches series CES-AP are interlocking devices without guard locking (type 4). The device meets the requirements according to EN IEC 60947-5-3. Devices with unicode evaluation possess a high coding level, devices with multicode evaluation possess a low coding level.

In combination with a movable guard and the machine control, this safety component prevents dangerous machine functions from occurring while the guard is open. A stop command is triggered if the guard is opened during the dangerous machine function.

This means:

- › Starting commands that cause a dangerous machine function must become active only when the guard is closed.
- › Opening the guard triggers a stop command.
- › Closing a guard must not cause automatic starting of a dangerous machine function. A separate start command must be issued. For exceptions, refer to EN ISO 12100 or relevant C-standards.

Before the device is used, a risk assessment must be performed on the machine, e.g. in accordance with the following standards:

- › EN ISO 13849-1
- › EN ISO 12100
- › EN IEC 62061

Correct use includes observing the relevant requirements for installation and operation, particularly based on the following standards:

- › EN ISO 13849-1
- › EN ISO 14119
- › EN IEC 60204-1

The safety switch is only allowed to be operated in conjunction with the intended EUCHNER CES actuators and the related connection components from EUCHNER. If different actuators or other connection components are used, EUCHNER provides no warranty for safe function.



### Important!

- › The user is responsible for the proper integration of the device into a safe overall system. For this purpose, the overall system must be validated, e.g. in accordance with EN ISO 13849-1.
- › It is only allowed to use components that are permissible in accordance with the table below.

Table 1: Possible combinations for CES components

Safety switch	Actuator			
	CES-A-BBA 071840	CES-A-BDA-18 156935	CES-A-BPA 098775	CES-A-BRN 100251
CES-AP-C01-... All types	●	●	●	●
Key to symbols	●	Combination possible		

### 3. Description of the safety function

Devices from this series feature the following safety functions:

#### Monitoring of the guard position (interlocking device according to EN ISO 14119)

- › Safety function:
  - The safety outputs are switched off when the guard is open (see chapter 6.4. *Switching states on page 7*).
- › Safety characteristics: category, Performance Level, PFH (see chapter 12. *Technical data on page 19*).

### 4. Exclusion of liability and warranty

In case of failure to comply with the conditions for correct use stated above, or if the safety regulations are not followed, or if any servicing is not performed as required, liability will be excluded and the warranty void.

### 5. General safety precautions

Safety switches fulfill personnel protection functions. Incorrect installation or tampering can lead to fatal injuries to personnel.

Check the safe function of the guard particularly

- › after any setup work
- › after the replacement of a system component
- › after an extended period without use
- › after every fault

Independent of these checks, the safe function of the safeguard should be checked at suitable intervals as part of the maintenance schedule.



#### **WARNING**

Danger to life due to improper installation or due to bypassing (tampering). Safety components perform a personnel protection function.

- › Safety components must not be bypassed, turned away, removed or otherwise rendered ineffective. On this topic pay attention in particular to the measures for reducing the possibility of bypassing according to EN ISO 14119:2025, section 8.
- › The switching operation must be activated only by actuators designated for this purpose.
- › Prevent bypassing by means of replacement actuators (only for multicode evaluation). For this purpose, restrict access to actuators and to keys for releases, for example.
- › Mounting, electrical connection and setup only by authorized personnel possessing the following knowledge:
  - specialist knowledge in handling safety components
  - knowledge about the applicable EMC regulations
  - knowledge about the applicable regulations on operational safety and accident prevention.



#### **Important!**

Prior to use, read the operating instructions and keep these in a safe place. Ensure the operating instructions are always available during mounting, setup and servicing. For this reason you should archive a printed copy of the operating instructions. You can download the operating instructions from [www.euchner.com](http://www.euchner.com).

### 6. Function

The safety switch monitors the position of movable guards. The safety outputs are switched on/off when the actuator is moved to/removed from the actuating range.

The system consists of the following components: coded actuator (transponder) and switch.

Whether the device learns the complete actuator code (unicode) or not (multicode) depends on the respective version.

- **Devices with unicode evaluation:** The actuator must be assigned to the safety switch by a teach-in operation so that it is detected by the system. This unambiguous assignment ensures a particularly high level of protection against tampering. The system thus possesses a high coding level.
- **Devices with multicode evaluation:** Unlike systems with unicode evaluation, on multicode devices a specific code is not requested but instead it is only checked whether the actuator is of a type that can be detected by the system (multicode evaluation). There is no exact comparison of the actuator code with the taught-in code in the safety switch (unicode evaluation). The system possesses a low coding level.

When the guard is closed, the actuator is moved toward the safety switch. When the operating distance is reached, power is supplied to the actuator by the switch and data are transferred.

If a permissible code is detected, the safety outputs are switched on.

The safety outputs are switched off when the guard is opened.

In the event of a fault in the safety switch, the safety outputs are switched off and the DIA LED illuminates red. The occurrence of faults is detected at the latest on the next demand to close the safety outputs (e.g. on starting).

#### 6.1. Door monitoring output

The door monitoring output is switched on as soon as a valid actuator is detected in the actuating range.

#### 6.2. Diagnostic output

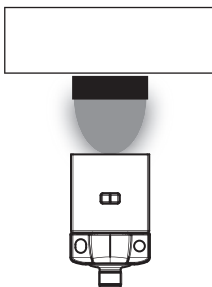
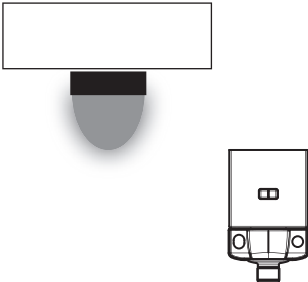
The diagnostic output is switched on in the event of a fault (switch-on condition as for DIA LED).

#### 6.3. Limit-range monitoring

If the safety door with the actuator should settle over time, the actuator can drift out of the read head actuating range. The device recognizes this situation and indicates that the actuator is in the limit range by flashing the STATE LED. This allows the safety door to be readjusted in time. See also chapter 11. *System status table on page 18.*

#### 6.4. Switching states

The detailed switching states for your switch can be found in the system status table (see chapter 11. *System status table on page 18*). All safety outputs, monitoring outputs and display LEDs are described there.

	Guard closed (actuator in the actuating range and permissible code detected)	Guard open (actuator not in the actuating range)
		
Safety outputs OA and OB	on	off
Monitoring output OUT	on	off

## 7. Changing the approach direction



### NOTICE

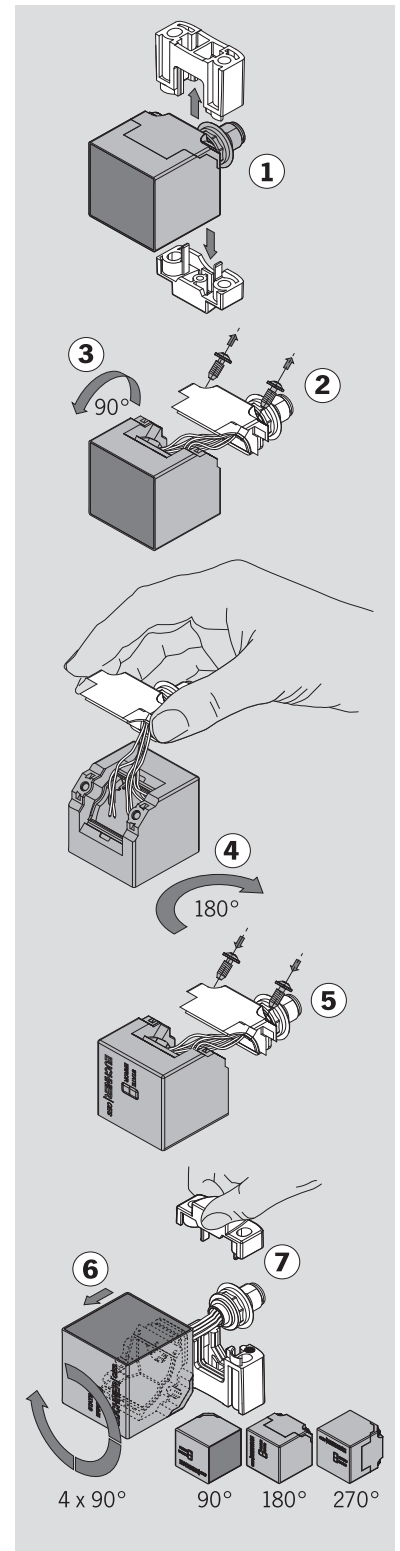
Risk of damage to equipment as a result of trapped cables or seals.

- › Make sure that the cables or seals are not trapped or torn off when the approach direction is changed.
- › Make sure that the flat seal is not trapped and that the profile seal is properly positioned in its guide, otherwise the sealing function is no longer ensured.

The active face of the read head can be adjusted in 5 directions. It is marked by the red face.

The plug connector can be realigned in 45° steps to change the direction of the cable outlet (if elbow connectors are used).

1. Remove the top part of the mounting base and push the bottom part of the mounting base off the read head.
2. Unscrew the screws on the fastening bracket.
3. Undo the read head from the fastening bracket and tilt the read head forward by 90°.  
➔ The active face is now pointing downward.
4. Hold the fastening bracket tight and turn the read head by 180°.
5. Re-tighten the screws for the read head on the fastening bracket. Tightening torque 0.6 Nm.
6. Turn the read head in 90° steps until the desired approach direction is reached. Change the alignment of the plug connector if necessary.
7. Push the read head onto the bottom part of the mounting base and re-assemble the mounting base.





### 8. Mounting



#### CAUTION

Safety switches must not be bypassed (bridging of contacts), turned away, removed or otherwise rendered ineffective.

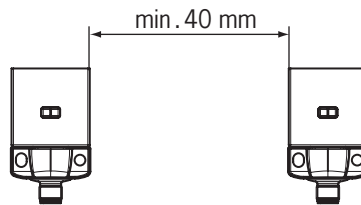
- Observe EN ISO 14119:2025, section 8, for information about reducing the possibilities for bypassing an interlocking device.



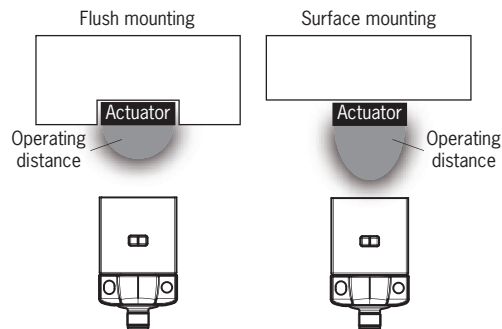
#### NOTICE

Risk of damage to equipment and malfunctions as a result of incorrect installation.

- Safety switches and actuators must not be used as an end stop.
- Observe EN ISO 14119:2025, sections 6.2 and 6.3, for information about mounting the safety switch and the actuator.
- From the assured release distance  $S_{ar}$ , the safety outputs are safely switched off.
- When mounting several safety switches/actuators, observe the stipulated minimum distance to avoid mutual interference



- If the actuator is installed flush, the operating distances change as a function of the installation depth and the guard material.



#### Note the following points:

- Actuator and safety switch must be easily accessible for inspection and replacement.
- Actuator and safety switch must be fitted so that
  - the front faces are at the minimum operating distance  $0.8 \times S_{a0}$  or closer when the guard is closed. To avoid entering the area of possible side lobes, a minimum distance is to be maintained in case of a side approach direction. See chapter 12. *Technical data*, section *Typical operating distance*, for the related actuator.
  - when the guard is open up to the distance  $S_{ar}$  (assured release distance), a hazard is excluded.
  - the actuator is positively mounted on the guard, e.g. by using the safety screws included.
  - they cannot be removed or tampered with using simple means.
- Pay attention to the maximum tightening torque for the read head or safety switch and actuator fastenings of 1 Nm.

## 9. Electrical connection



### WARNING

In the event of a fault, loss of the safety function due to incorrect connection.

- › To ensure safety, both safety outputs must always be evaluated.
- › Monitoring outputs must not be used as safety outputs.
- › Lay the connecting cables with protection to prevent the risk of short circuits.



### CAUTION

Risk of damage to equipment or malfunctions as a result of incorrect connection.

- › The device generates its own test pulses on the output lines OA/OB. A downstream control system must tolerate these clock pulses, which may have a length of up to 0.4 ms. No clock pulses are output when the safety outputs are switched off.
- › The inputs on a connected evaluation unit must be positive switching, as the two outputs on the safety switch deliver a level of +24 V in the switched-on state.
- › All electrical connections must either be isolated from the mains supply by a safety transformer according to IEC 61558-2-6 with limited output voltage in the event of a fault, or by other equivalent insulation measures (PELV).
- › All electrical outputs must have an adequate protective circuit for inductive loads. The outputs must be protected with a free-wheeling diode for this purpose. RC interference suppression units must not be used.
- › Power devices which are a powerful source of interference must be installed in a separate location away from the input and output circuits for signal processing. The cable routing for safety circuits should be as far away as possible from the cables of the power circuits.
- › To avoid EMC interference, the physical environmental and operating conditions at the installation site of the device must comply with the requirements according to the standard EN 60204-1 (EMC).
- › Pay attention to any interference fields from devices such as frequency converters or induction heating systems. Observe the EMC instructions in the manuals from the respective manufacturer.




### Important!

If the device does not appear to function when operating voltage is applied (e.g. green STATE LED does not flash), the safety switch must be returned unopened to the manufacturer.

### 9.1. Notes on



#### Important!

- This device is intended to be used with a Class 2 power source in accordance with UL1310. As an alternative an LV/C (Limited Voltage/Current) power source with the following properties can be used:
  - This device shall be used with a suitable isolating source in conjunction with a fuse in accordance with UL248. The fuse shall be rated max. 3.3 A and be installed in the max. 30 V DC power supply to the device in order to limit the available current to comply with the UL requirements. Please note possibly lower connection ratings for your device (refer to the technical data).
- For use and application as per the requirements of <sup>1)</sup>, a connecting cable listed under the UL category code CYJV2 or CYJV must be used.

1) Note on the scope of the UL approval: the devices have been tested as per the requirements of UL508 and CSA/C22.2 no. 14 (protection against electric shock and fire). Only for applications as per NFPA 79 (Industrial Machinery).

### 9.2. Safety in case of faults

- The operating voltage  $U_B$  is reverse polarity protected.
- The safety outputs are short circuit-proof.
- A short circuit between the safety outputs is detected by the switch.
- A short circuit in the cable can be excluded by laying the cable with protection.

### 9.3. Fuse protection for power supply

The power supply must be provided with fuse protection depending on the number of switches and the current required for the outputs. The following rules apply:

#### Max. current consumption of an individual switch $I_{max}$

$$I_{max} = I_{UB} + I_{OA+OB}$$

$$I_{UB} = \text{Switch operating current (50 mA)}$$

$$I_{OA+OB} = \text{Load current of safety outputs OA + OB (2 x max. 400 mA)}$$

### 9.4. Requirements for connecting cables



#### CAUTION

Risk of damage to equipment or malfunctions as a result of incorrect connecting cables.

- Use connection components and connecting cables from EUCHNER.
- If other connection components are used, the requirements in the following table apply. EUCHNER provides no warranty for safe function in case of failure to comply with these requirements.
- Observe the maximum cable length of 200 m.

Observe the following requirements with respect to the connecting cables:

Parameter	Value				Unit
	6-pin	M8 / 8-pin	M12 / 5-pin	M12 / 5-pin	
Recommended cable type	LIYY 6 x 0.14	LIYY 8 x 0.14	LIYY 5 x 0.25	LIYY 5 x 0.34	mm <sup>2</sup>
Cable	6 x 0.14	8 x 0.14	5 x 0.25	5 x 0.34	mm <sup>2</sup>
Cable resistance R max.	150	150	78	58	Ω/km
Inductance L max.	0.66	0.65	0.64	0.53	mH/km
Capacitance C max.	128	120	60	100	nF/km

## 9.5. Connector assignment of safety switch CES-AP-C01

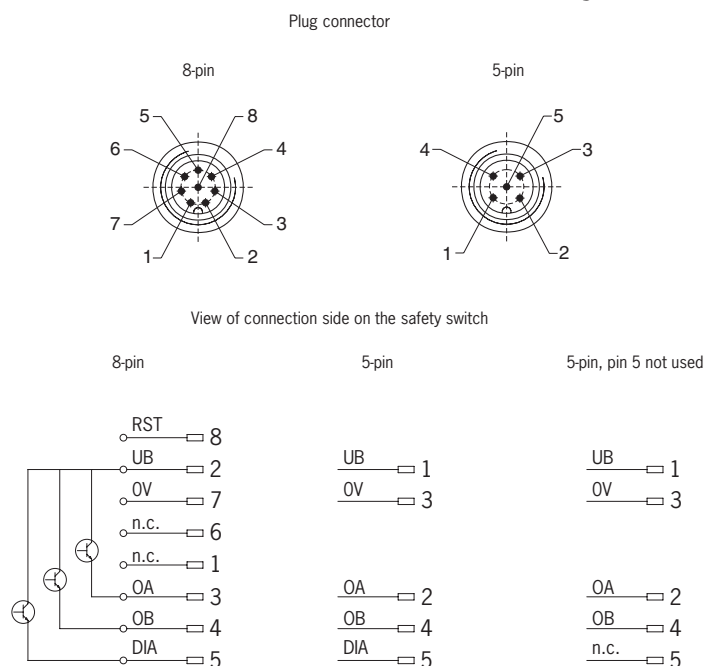


Fig. 1: Connector assignment of safety switch CES-AP-C01

Pin Plug connector 8-pin	Designation	Description	Conductor coloring
1	n.c.	Not used	WH
2	UB	Power supply, DC 24 V	BN
3	OA	Safety output, channel A	GN
4	OB	Safety output, channel B	YE
5	DIA	Monitoring output (diagnostics)	GY
6	n.c.	Not used	PK
7	OV	Ground, DC 0 V	BU
8	RST	Reset input	RD

Pin Plug connector 5-pin	Pin Plug connector 5-pin, pin 5 not used	Designation	Description	Conductor coloring
1	1	UB	Power supply, DC 24 V	BN
2	2	OA	Safety output, channel A	WH
3	3	OV	Ground, DC 0 V	BU
4	4	OB	Safety output, channel B	BK
5	-	DIA	Monitoring output (diagnostics)	GY

### 9.6. Connection

The switch can be reset via the RST input. To do this, a voltage of 24 V is applied to the RST input for at least 3 seconds. The RST input must be connected to 0 V if it is not used (only devices with plug connector M12, 8-pin).



#### **WARNING**

In the event of a fault, loss of the safety function due to incorrect connection.  
 ▶ To ensure safety, both safety outputs (OA and OB) must always be evaluated.



#### **Important!**

The example shows only an excerpt that is relevant for the connection of the CES system. The example illustrated here does not show complete system planning. The user is responsible for safe integration into the overall system. Detailed application examples can be found at [www.euchner.com](http://www.euchner.com). Simply enter the order number of your switch in the search box. You will find all available connection examples for the device in *Downloads*.

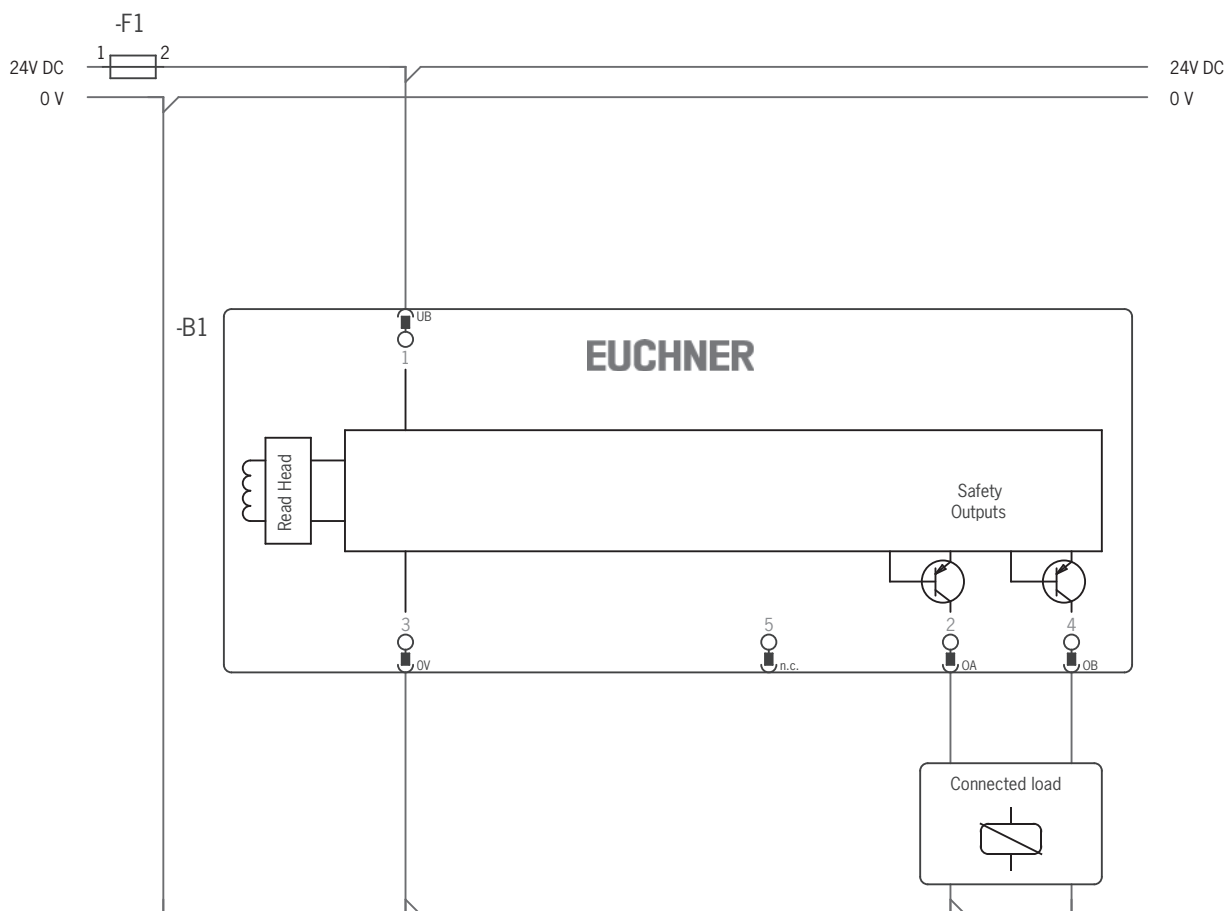


Fig. 2: Connection example CES-AP-...

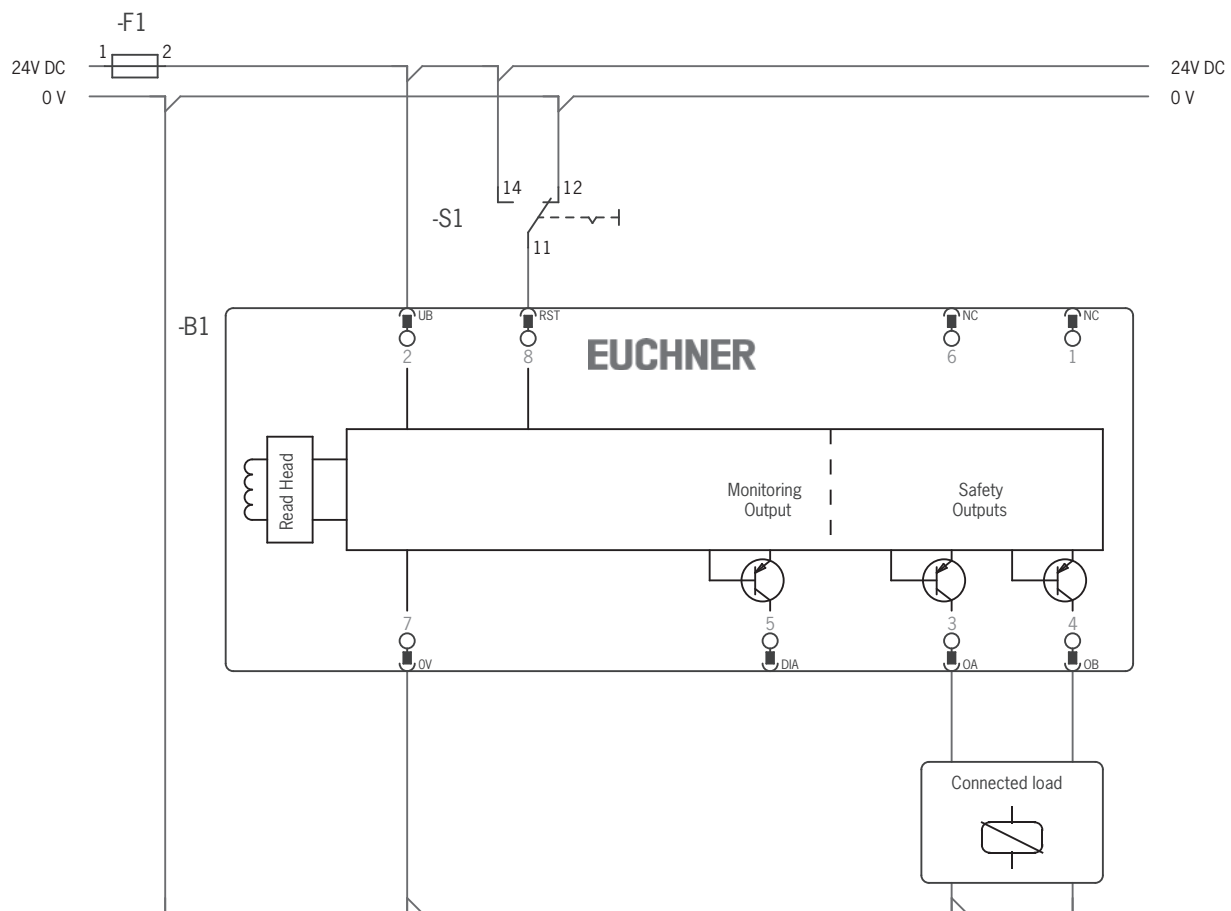


Fig. 3: Connection example CES-AP-... with reset button

9.7. Notes on operation with safe control systems


- Observe the following guidelines for connection to safe control systems:
- Use a common power supply for the control system and the connected safety switches.
  - A pulsed power supply must not be used for  $U_B$ . Tap the supply voltage directly from the power supply unit. If the power supply is connected to a terminal of a safe control system, this output must provide sufficient electrical current.
  - The safety outputs (OA and OB) can be connected to the safe inputs of a control system. Prerequisite: The input must be suitable for pulsed safety signals (OSSD signals, e.g. from light grids). The control system must tolerate test pulses on the input signals. This normally can be set up by parameter assignment in the control system. Observe the notes of the control system manufacturer. For the pulse duration of your safety switch, refer to chapter 12. *Technical data on page 19.*

A detailed example of connecting and setting the parameters of the control system is available for many devices at [www.euchner.com](http://www.euchner.com), in the area *Downloads/Applications/CES*. The features of the respective device are dealt with there in greater detail.

9.8. Devices for direct connection to IP67 field modules

The version CES-AP-...-SB-... (M12, 5-pin; pin 5 not assigned) is optimized for connection to decentralized peripheral systems with M12 plug connector, such as the ET200pro series from Siemens. The devices are parameterized and connected like an OSSD (e.g. like light curtains).

If flying leads are used, connection to IP20 input and output modules (e.g. ET200SP) is naturally also possible.



**Important!**

Observe the following notes prior to connection:

- Parameter assignment must be performed for the input/output modules (see application example at [www.euchner.com](http://www.euchner.com), in the area *Downloads/Applications/CES*).
- Additionally observe notes from the control system manufacturer where necessary.

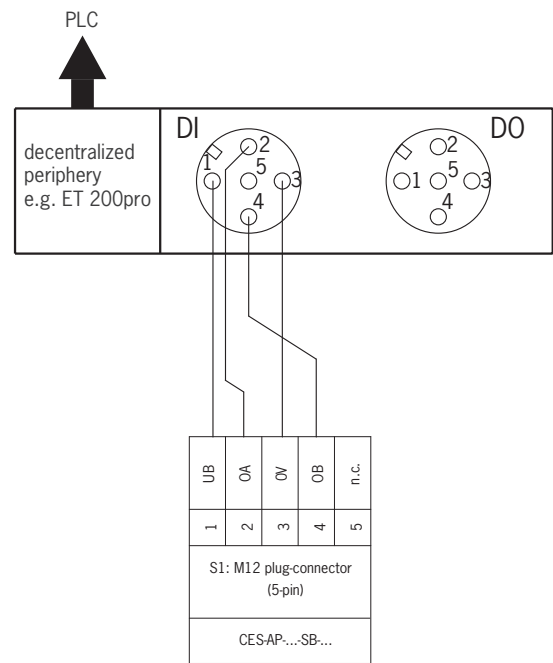





Fig. 4: Connection example for version for connection to decentralized peripheral systems

## 10. Setup

### 10.1. LED displays

LED	Color	State	Meaning
STATE	green	illuminated 	Normal operation
		flashing 	- Teach-in operation or power-up - Actuator in limit range (from V0.1.2) (for further signal function, see chapter 11. System status table on page 18)
DIA	red	illuminated 	- Internal electronics fault - Fault at the inputs/outputs

### 10.2. Teach-in function for actuator (only for unicode evaluation)

The actuator must be allocated to the safety switch using a teach-in function before the system forms a functional unit.

During a teach-in operation, the safety outputs and the monitoring output OUT are switched off, i.e. the system is in the safe state.



#### Important!

- The teach-in operation may be performed only if the device functions flawlessly. The red DIA LED must not be illuminated.
- The safety switch disables the code of the preceding device if teach-in is carried out for a new actuator. Teach-in is not possible again immediately for this device if a new teach-in operation is carried out. The disabled code is enabled again in the safety switch only after a third code has been taught-in.
- The safety switch can be operated only with the last actuator taught-in.
- The number of teach-in operations is unlimited.
- If the switch detects the actuator that was most recently taught-in when in teach-in standby, this state is ended immediately and the switch changes to normal operation.
- If the actuator to be taught-in is in the actuating range for less than 60 s, it will not be activated and the most recently taught-in actuator will remain saved.
- After an unsuccessful teach-in operation, the switch changes to normal operation.

#### 10.2.1. Preparing device for the teach-in operation and teaching-in actuator

1. Apply operating voltage to the safety switch.
  - ➔ A self-test is performed for approx. 0.5 s. After this, the LED flashes cyclically three times and signals teach-in standby.  
Teach-in standby remains active for approx. 3 minutes.
2. Move new actuator to the read head (observe distance  $< S_{a0}$ ).
  - ➔ Teach-in operation starts, green LED flashes (approx. 1 Hz). During the teach-in operation, the safety switch checks whether the actuator is a disabled actuator. Provided this is not the case, the teach-in operation is completed after approx. 60 seconds, and the green LED goes out. The new code has now been stored, and the old code is disabled.
3. To activate the new actuator code from the teach-in operation in the safety switch, the operating voltage to the safety switch must then be switched off for min. 3 seconds.



## 10.3. Functional check



### WARNING

Danger of fatal injury as a result of faults in installation and the functional check.

- › Before carrying out the functional check, make sure that there are no persons in the danger area.
- › Observe the valid accident prevention regulations.

### 10.3.1. Electrical function test

After installation and any fault, the safety function must be fully checked. Proceed as follows:

1. Switch on operating voltage.
  - ➔ The machine must not start automatically.
  - ➔ The safety switch carries out a self-test. The green STATE LED then flashes at regular intervals.
2. Close all guards.
  - ➔ The machine must not start automatically.
  - ➔ The green STATE LED illuminates continuously.
3. Enable operation in the control system.
4. Open the guard.
  - ➔ The machine must switch off and it must not be possible to start it as long as the guard is open.
  - ➔ The green STATE LED flashes at regular intervals.

Repeat steps 2 - 4 for each guard.

## 11. System status table

Operating mode	Actuator/door position	Safety outputs OA and OB	LED indicator Output		State
			STATE (green)	DIA (red)	
Normal operation	closed	on			Normal operation, door closed
	closed	on	invert-ed flash burst		Normal operation, door closed, actuator in the limit range ➔ Re-adjust door
	open	off	1 x		Normal operation, door open
	open	off	2 x		Normal operation, door open; no actuator was taught in successfully during initial setup
Teach-in operation (only unicode)	open	off	3 x		Door open, device is ready for teach-in for another actuator (only short time after power-up)
	closed	off	1 Hz		Teach-in operation
	X	off			Positive acknowledgment after completion of teach-in operation
Fault display	closed	off	3 x		Defective actuator (e.g. error in code or code not readable)
	X	off	4 x		Output fault (e.g. short circuits, loss of switching ability)
	X	off	5 x		- Internal fault (e.g. component fault, data error) - Fault on the power supply (e.g. shutdown pulse duration for pulsed power supply too long)
Key to symbols			LED not illuminated		
			LED illuminated		
	10 Hz (8 s)		LED flashes for 8 seconds at 10 Hz		
	3 x		LED flashes three times; cycle time 7 s		
	X		Any state		

After the cause has been remedied, faults can generally be reset by opening and closing the guard. If the fault is still displayed afterward, briefly interrupt the power supply. Contact the manufacturer if the fault could not be reset after restarting.



### Important!

If you do not find the displayed device status in the system status table, this indicates an internal device fault. In this case, you should contact the manufacturer.

### 12. Technical data



#### NOTICE

If a data sheet is included with the product, the information on the data sheet applies.

#### 12.1. Technical data for safety switch CES-AP-C01-...

Parameter	Value			Unit
	min.	typ.	max.	
Housing material	PBT plastic			
Dimensions	Acc. to EN 60947-5-2			
Weight	0.12			kg
Ambient temperature at $U_B = DC\ 24\ V$	- 20	-	+ 55	°C
Storage temperature	- 25	-	+ 70	
Degree of protection	IP67			
Safety class	III			
Degree of contamination	3			
Installation position	Any			
Connection	M12 plug connector, 5-pin or 8-pin			
Operating voltage $U_B$ (regulated, residual ripple < 5%)	24 ± 15% (PELV)			V DC
Current consumption with no load on outputs	-	50	-	mA
External fuse (operating voltage)	0.25	-	8	A
Safety outputs OA/OB	Semiconductor outputs, p-switching, short circuit-proof			
- Output voltage $U(OA)/U(OB)$ <sup>1)</sup>				
HIGH $U(OA)$	$U_B-1.5$	-	$U_B$	V DC
HIGH $U(OB)$				
LOW $U(OA)/U(OB)$	0		1	
Switching current per safety output	1	-	400	mA
Utilization category acc. to EN IEC 60947-5-2	DC-13 24 V 400 mA Caution: outputs must be protected with a free-wheeling diode in case of inductive loads.			
Off-state current $I_r$ <sup>2)</sup>	-	-	0.25	mA
Monitoring output DIA <sup>1)</sup>	p-switching, short circuit-proof			
- Output voltage	$0.8 \times U_B$	-	$U_B$	V DC
- Max. load	-	200	-	mA
Rated insulation voltage $U_i$	-	75	-	V
Rated impulse withstand voltage $U_{imp}$	-	0.5	-	kV
Shock and vibration resistance	Acc. to EN IEC 60947-5-3			
Switching frequency	-	-	1	Hz
Repeat accuracy R acc. to EN IEC 60947-5-2	≤ 10			%
EMC protection requirements	Acc. to EN IEC 60947-5-3			
Ready delay	-	0.5	-	s
Risk time	-	-	260	ms
Turn-on time	-	-	400	ms
Discrepancy time	-	-	10	ms
Test pulse duration	-	-	0.4	ms
<b>Characteristics acc. to EN ISO 13849-1</b>				
<b>Monitoring of the guard position</b>				
Category	4			
Performance Level	PL e			
PFH	$2.1 \times 10^{-9} / h$			
Mission time	20			years

1) Values at a switching current of 50 mA without taking into account the cable lengths.

2) Maximum current at an output in switched-off state.

### 12.1.1. Typical system times

Refer to the technical data for the exact values.

**Ready delay:** After switch-on, the device carries out a self-test. The system is ready for operation only after this time.

**Turn-on time of safety outputs:** The max. reaction time  $t_{on}$  is the time from the moment when the actuator is in the actuating range to the moment when the safety outputs switch on.

**Risk time according to EN 60947-5-3:** If an actuator moves outside the actuating range, the safety outputs (OA and OB) are deactivated at the latest after the risk time.

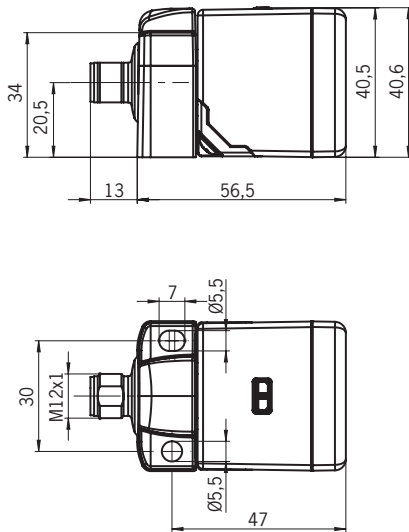
**Discrepancy time:** The safety outputs (OA and OB) switch with a slight time offset. They have the same signal state no later than after the discrepancy time.

**Test pulses at the safety outputs:** The device generates its own test pulses on the output lines OA/OB. A downstream control system must tolerate these test pulses.

This can usually be set up in the control systems by parameter assignment. If parameter assignment is not possible for your control system or if shorter test pulses are required, contact our Service team.

The test pulses are output only if the safety outputs are switched on.

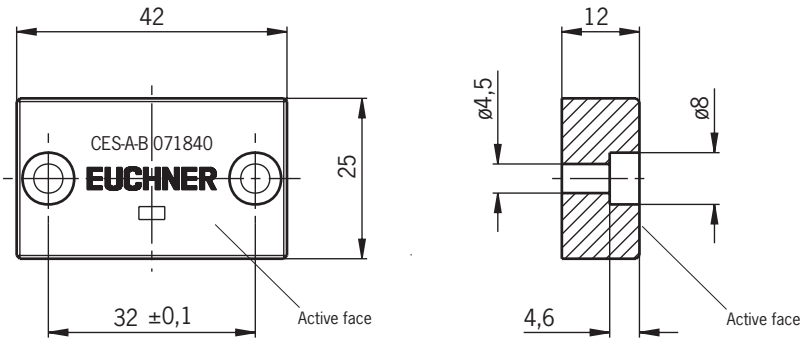
### 12.1.2. Dimension drawing for safety switch CES-AP-C01-...



12.2. Technical data for actuator CES-A-BBA

Parameter	Value			Unit
	min.	typ.	max.	
Housing material	Plastic (PPS)			
Dimensions	42 x 25 x 12			mm
Weight	0.02			kg
Ambient temperature	-25	-	+70	°C
Degree of protection	IP65/IP67/IP69/IP69K			
Installation position	Active face opposite read head			
Power supply	Inductive via read head			

12.2.1. Dimension drawing



**NOTICE**  
2 safety screws M4x14 included

12.2.2. Operating distances

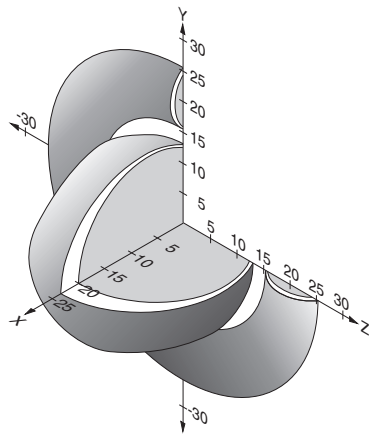
Operating distance for center offset  $m = 0$  <sup>1)</sup>

Parameter	Value			Unit
	min.	typ.	max.	
Operating distance	-	18	-	mm
Assured operating distance $s_{ao}$	15	-	-	
Switching hysteresis	1	3	-	
Assured release distance $s_{ar}$	-	-	45	

1) The values apply to surface mounting of the actuator on metal.

### 12.2.3. Typical operating distance

(only in combination with actuator CES-ABBA)



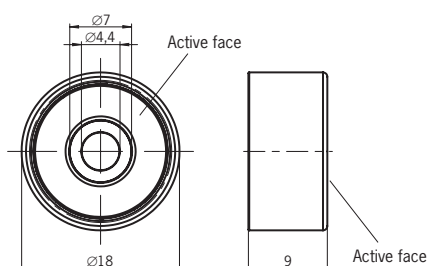
For a side approach direction for the actuator and safety switch, a minimum distance of  $s = 4$  mm must be maintained so that the actuating range of the side lobes is not entered.

Fig. 5: Typical operating distance

### 12.3. Technical data for actuator CES-A-BDA-18

Parameter	Value			Unit
	min.	typ.	max.	
Housing material - Sleeve - Active face	PBT-GF30, thermoplastic plastic PEEK 450, thermoplastic plastic			
Fixing screw tightening torque	2			Nm
Dimensions	Ø 18 x 9			mm
Weight	0.003			kg
Ambient temperature	-25	-	+70	°C
Degree of protection	IP65/IP67			
Installation position	Active face opposite read head			
Power supply	Inductive via read head			

#### 12.3.1. Dimension drawing



#### NOTICE

1 safety screw M4x14 included

#### 12.3.2. Operating distances

Operating distance for center offset  $m = 0$  <sup>1)</sup>

Parameter	Value			Unit
	min.	typ.	max.	
Operating distance	-	19	-	mm
Assured operating distance $s_{ao}$	10	-	-	
Switching hysteresis	1	3	-	
Assured release distance $s_{ar}$	-	-	45	

1) The values apply to surface mounting of the actuator on metal.

### 12.3.3. Typical operating distance

(only in combination with actuator CES-ABDA-18 on surface mounting)

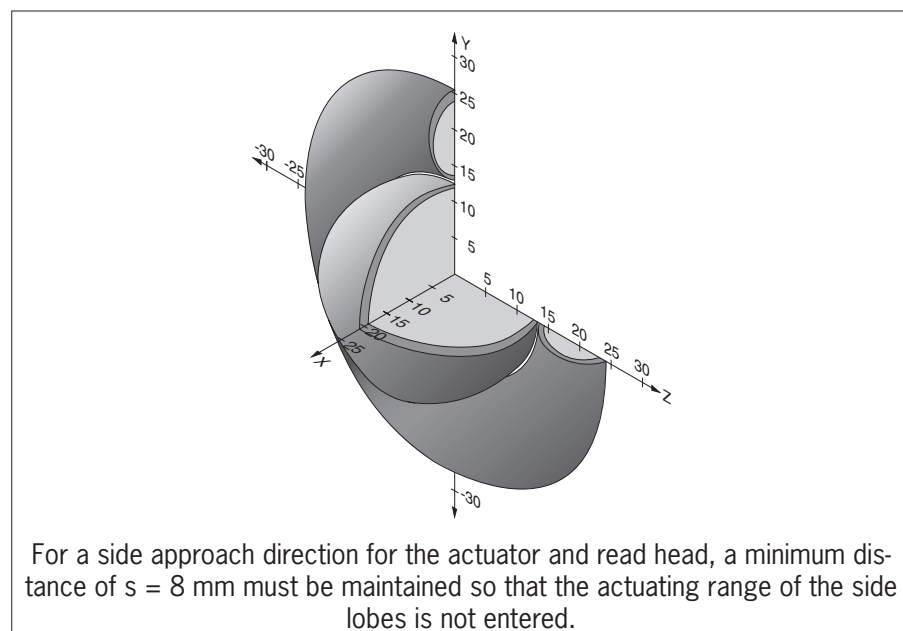


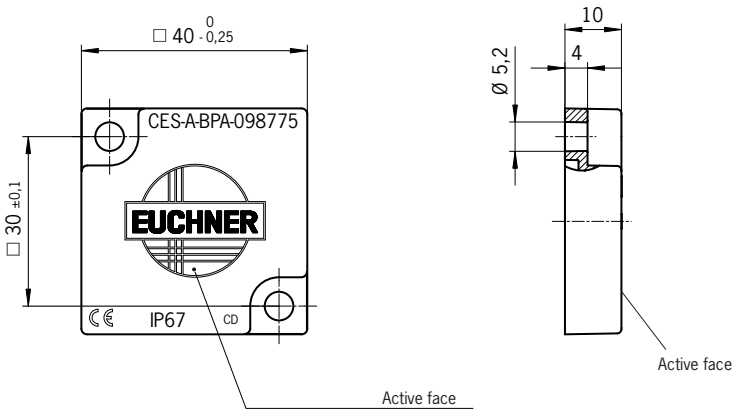
Fig. 6: Typical operating distance



12.4. Technical data for actuator CES-A-BPA

Parameter	Value			Unit
	min.	typ.	max.	
Housing material	PBT			
Dimensions	40 x 40 x 10			mm
Weight	0.025			kg
Ambient temperature	- 25	-	+ 70	°C
Degree of protection	IP65/IP67/IP69/IP69K			
Installation position	Active face opposite read head			
Power supply	Inductive via read head			

12.4.1. Dimension drawing



**NOTICE**  
2 safety screws M5x10 included.

12.4.2. Operating distances

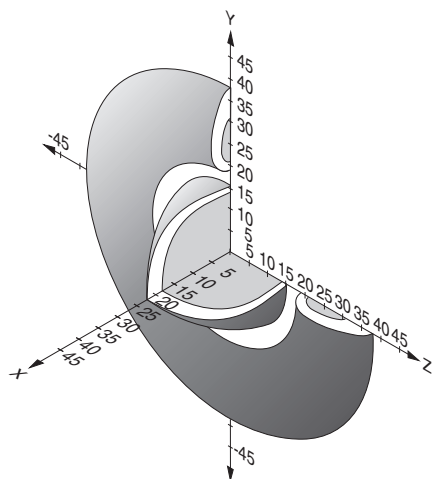
Operating distance for center offset  $m = 0$  <sup>1)</sup>

Parameter	Value			Unit
	min.	typ.	max.	
Operating distance	-	22	-	mm
Assured operating distance $s_{ao}$	18	-	-	
Switching hysteresis	1	2	-	
Assured release distance $s_{ar}$	-	-	58	

1) The values apply to surface mounting of the actuator on metal.

### 12.4.3. Typical operating distance

(only in combination with actuator CES-ABPA on surface mounting)



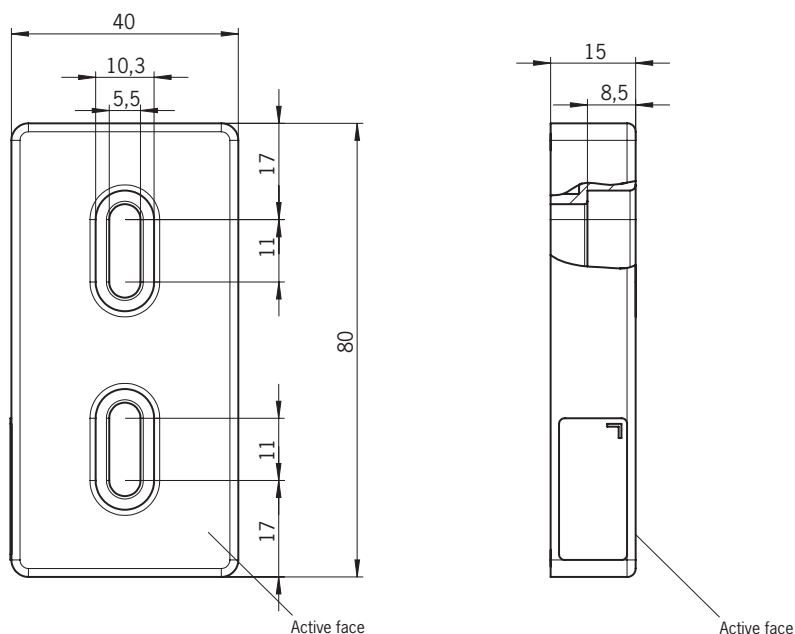
For a side approach direction for the actuator and read head, a minimum distance of  $s = 6 \text{ mm}$  must be maintained so that the actuating range of the side lobes is not entered.

Fig. 7: Typical operating distance

### 12.5. Technical data for actuator CES-A-BRN

Parameter	Value			Unit
	min.	typ.	max.	
Housing material	PPS			
Dimensions	80 x 40 x 15			mm
Weight	0.06			kg
Ambient temperature	- 25	-	+ 70	°C
Degree of protection	IP67			
Installation position	Active face opposite read head			
Power supply	Inductive via read head			

#### 12.5.1. Dimension drawing



#### NOTICE

2 safety screws M5x16 included.

#### 12.5.2. Operating distances

Operating distance for center offset  $m = 0$  <sup>1)</sup>

Parameter	Value			Unit
	min.	typ.	max.	
Operating distance	-	27	-	mm
Assured operating distance $s_{ao}$	20	-	-	
Switching hysteresis	-	3	-	
Assured release distance $s_{ar}$	-	-	75	

1) The values apply to surface mounting of the actuator on metal.

### 12.5.3. Typical operating distance

(only in combination with actuator CES-A-BRN on surface mounting on metal)

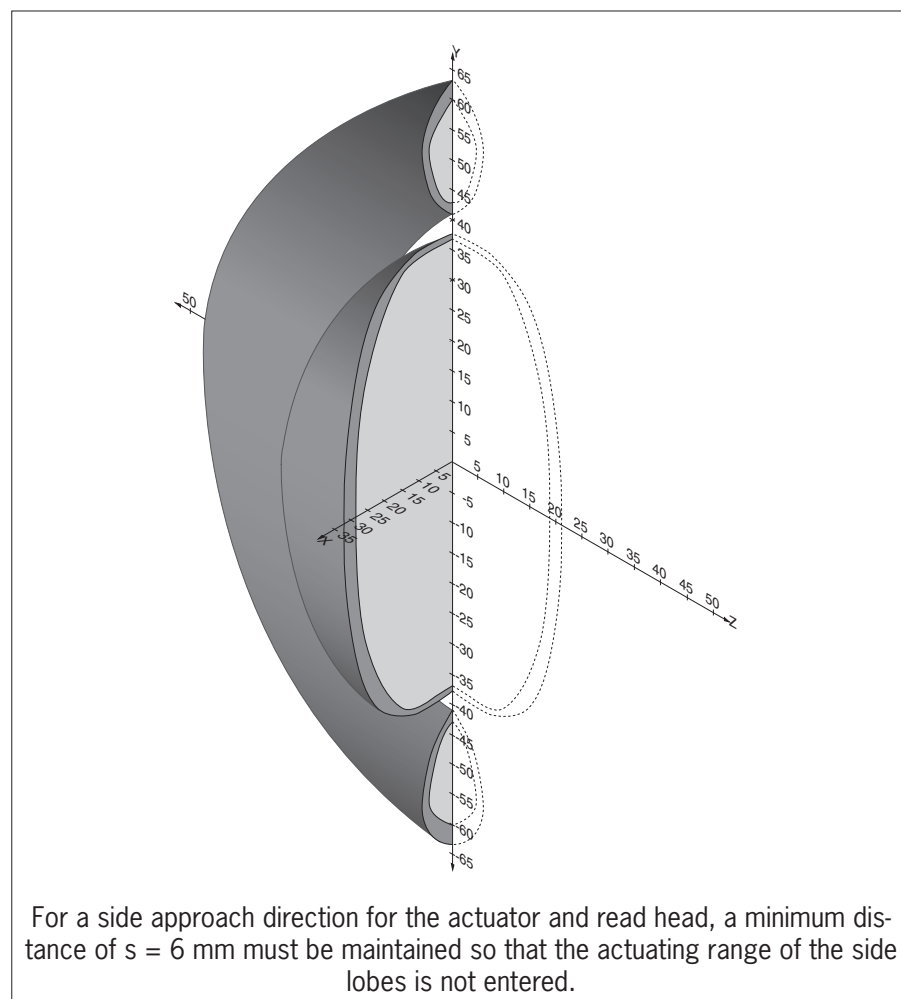


Fig. 8: Typical operating distance

## 13. Ordering information and accessories



### Tip!

Suitable accessories, e.g. cables or assembly material, can be found at [www.euchner.com](http://www.euchner.com). To order, enter the order number of your item in the search box and open the item view. Accessories that can be combined with the item are listed in *Accessories*.

## 14. Inspection and service



### WARNING

Loss of the safety function because of damage to the device.

- › In case of damage, the entire device must be replaced.
- › Only accessories or spare parts that can be ordered from EUCHNER may be replaced.

Regular inspection of the following is necessary to ensure trouble-free long-term operation:

- › Check the switching function (see chapter 10.3. *Functional check on page 17*)
- › Check the secure mounting of the devices and the connections
- › Check for contamination

No servicing is required. Repairs to the device are only allowed to be made by the manufacturer.



### NOTICE

The year of manufacture can be seen in the lower right corner of the type label. The current version number in the format (VX.X.X) can also be found on the device.

## 15. Service

If servicing is required, please contact:

EUCHNER GmbH + Co. KG  
Kohlhammerstraße 16  
70771 Leinfelden-Echterdingen

### Service telephone:

+49 711 7597-500

### E-mail:

[support@euchner.de](mailto:support@euchner.de)

### Internet:

[www.euchner.com](http://www.euchner.com)

## 16. Declaration of conformity

The product complies with the requirements according to

- › Machinery Directive 2006/42/EC (until January 19, 2027)
- › Machinery Regulation (EU) 2023/1230 (from January 20, 2027)

The EU declaration of conformity can be found at [www.euchner.com](http://www.euchner.com). Enter the order number of your device in the search box. The document is available under *Downloads*.

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