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1. About this document

1.1. Scope

This document is valid for all bus modules MBM-PN-...-MLI-... (PROFINET). It serves as a system and configuration manual for all module combinations that can be operated with this bus module.

These operating instructions, the document *Safety information*, the operating instructions for the modules connected and any associated data sheets form the complete user information for your system.

Series	Output family	Module connection type	Product version (hardware version)	Firmware version
MBM-...	...PN-...	...MLI-...	V2.1.X V2.2.X	V2.1.X V2.2.X V2.3.X



Important!

A firmware update might have been performed on your device. Make sure that the device documentation corresponding to the update is available and is observed.

1.1.1. Notes on other product versions

Make sure to use the operating instructions valid for your product version. Please contact our Service department if you have any questions.

1.2. Target group

Design engineers and installation planners for safety systems on machines, as well as setup and servicing staff possessing special expertise in handling safety components as well as expertise in the installation, setup, programming and diagnostics of programmable logic controllers (PLCs) and bus systems.

1.3. Key to symbols

Symbol/depiction	Meaning
	Printed document
	Document is available for download at www.euchner.com
 DANGER WARNING CAUTION	Safety precautions Danger of death or severe injuries Warning about possible injuries Caution Slight injuries possible
 NOTICE Important!	Notice about possible device damage Important information
Tip	Useful information

1.4. Supplementary documents

The overall documentation for this device consists of the following documents:

Document title (document number)	Contents	
Safety information (2525460)	Basic safety information	
Operating instructions (MAN20001743)	(this document)	
Operating instructions for the connected modules and their submodules	Device-specific information for the related module and the installed submodules	
Declaration of conformity	Declaration of conformity	
Release notes	Any firmware update report	
Any supplementary data sheets	Item-specific information about deviations or additions	



Important!

Always read all documents to gain a complete overview of safe installation, setup and use of the device. The documents can be downloaded from www.euchner.com. For this purpose, enter the doc. no. or the order number for the device in the search box.

2. Correct use

The bus module MBM-PN-...-MLI-... (PROFINET) is operated as an IO device on PROFINET (PROFIsafe). The bus module MBM communicates with the modules/submodules connected and evaluates all relevant information. It processes these data and then transmits them on the connected bus to a control system.

Before the device is used, a risk assessment must be performed on the machine, e.g. in accordance with the following standards:

- EN ISO 13849-1
- EN ISO 12100
- EN IEC 62061

Correct use includes observing the relevant requirements for installation and operation, particularly based on the following standards:

- EN ISO 13849-1
- EN ISO 14119
- EN IEC 60204-1

The bus module MBM is allowed to be combined only with suitable modules that have an MLI interface. You will find more detailed information on compatibility in the operating instructions for the related MLI device. See also *Table 1: Combination options for modules with MLI technology*. A maximum of 18 modules or submodules can be operated on one bus module MBM.

On the unauthorized modification of system components, EUCHNER provides no warranty for function.

The customer is responsible for the safe overall function, especially for the safe integration into the PROFIsafe environment.



Important!

- The user is responsible for the proper integration of the device into a safe overall system. For this purpose, the overall system must be validated, e.g. in accordance with EN ISO 13849-1.
- Correct use requires observing the permissible operating parameters (see chapter 15. *Technical data on page 57*).
- If a data sheet is included with the product, the information on the data sheet applies.

Table 1: Combination options for modules with MLI technology

Bus module	Basic modules	Handle module	Submodules	Submodules
		MGB2-H-... from V1.0.0	MSM-P-... MSM-R-... MSM-N-...	MSM-K-...
MBM-.-MLI from V2.0.0	Interlocking/locking module MGB2-I-.-MLI/MGB2-L-.-MLI from V1.4.0	●	●	-
	Expansion Module MCM-.-MLI	-	●	-
Key to symbols		●	Combination possible	
		-	Combination not possible	

2.1. Notes on cybersecurity

EUCHNER components and systems must not be integrated into public networks. EUCHNER components are approved only for use in private networks. Use a VPN for remote access.

3. Description of the safety function

The safety function of the bus module MBM comprises evaluating the safety data transmitted from the overall system (e.g. from installed guard locking devices, emergency stop devices, enabling switches, etc.) and forwarding these data on a bus system connected. The number of safe devices in an overall system is limited to 12. Depending on the modules and submodules connected, the overall system can include the following safety functions:

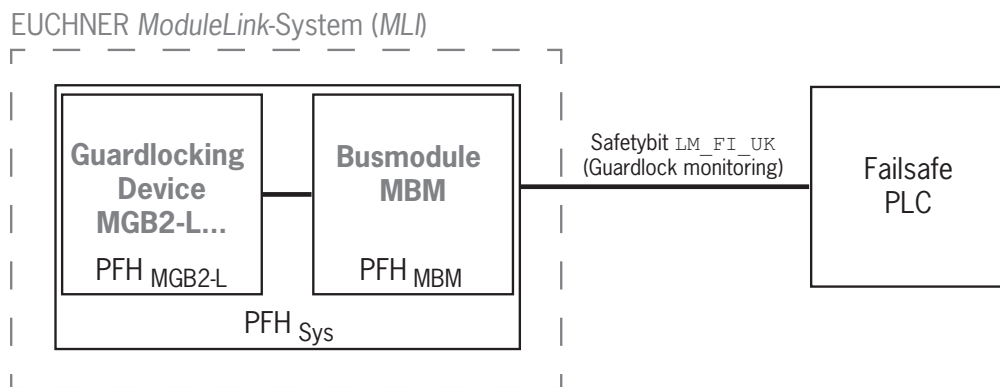
3.1. Safety functions in combination with an interlocking or locking module MGB2-I or MGB2-L

The following applies to MGB2-L...:

Monitoring of guard locking and the position of the guard (interlocking device with guard locking according to EN ISO 14119)

› Safety function:

- When guard locking is released, safety bit LM_FI_UK (ÜK) = 0 (monitoring of the locking element).
- When the guard is open, safety bit LM_FI_SK (SK) = 0 (monitoring of the position of the guard).
- Guard locking can be activated only when the bolt tongue is located in the locking module (prevention of inadvertent locking position (faulty closure protection)).



› Safety characteristics:

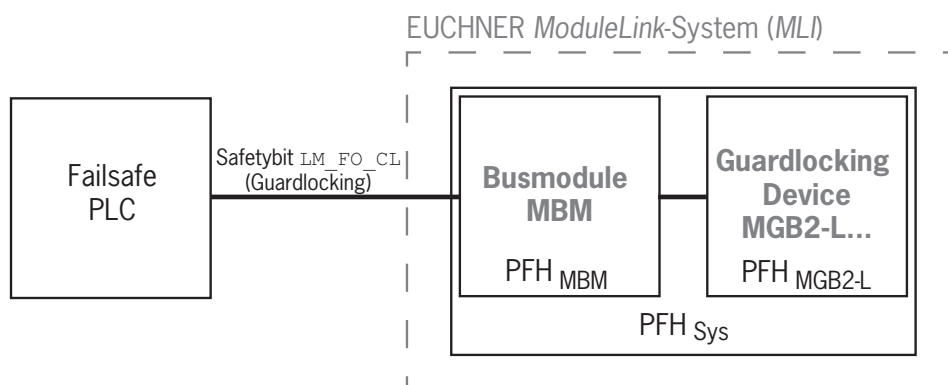
Category, Performance Level, PFH

Control of guard locking (safety bit LM_FO_CL ; applies only to guard locking devices according to the closed-circuit current principle)

› Safety function:

- If the device is used as guard locking for personnel protection, control of guard locking must be regarded as a safety function.

The safety level of guard locking control is determined by the system PFH_{sys} and by the external control (e.g. safe PLC).



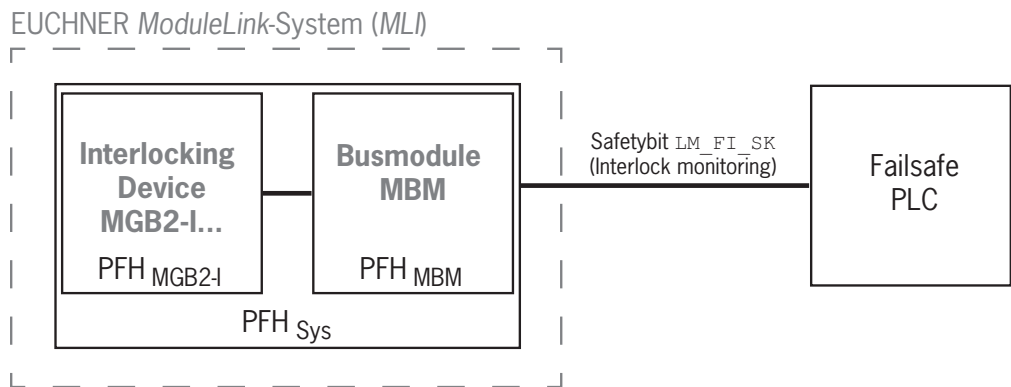
› Safety characteristics of the bus module and the locking module:

Category, Performance Level, PFH

The following applies to MGB2-I... (or a correspondingly configured MGB2-L2):

Monitoring of the guard position (interlocking device according to EN ISO 14119)

- › Safety function: When the guard is open, safety bit LM_FI_SK (SK) = 0. (See chapter 12.2. Data blocks for interlocking/locking module MGB2-I / MGB2-L.)

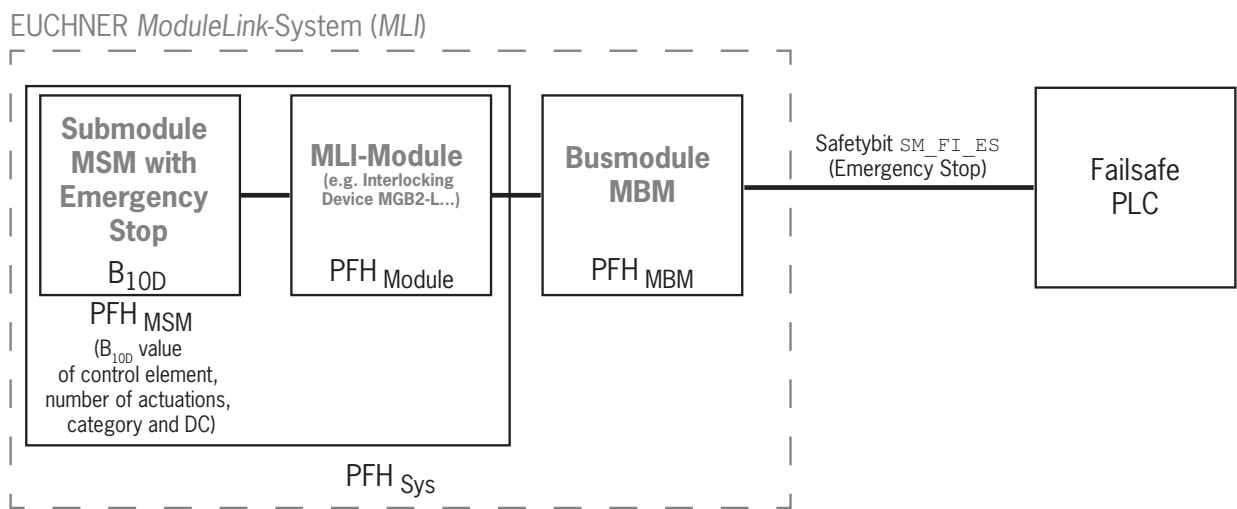


- › Safety characteristics:
Category, Performance Level, PFH
(You will find the reliability values according to EN 13849-1 in the technical data.)

3.2. Safety functions on submodules with emergency stop

Emergency stop (emergency stop device according to EN ISO 13850)

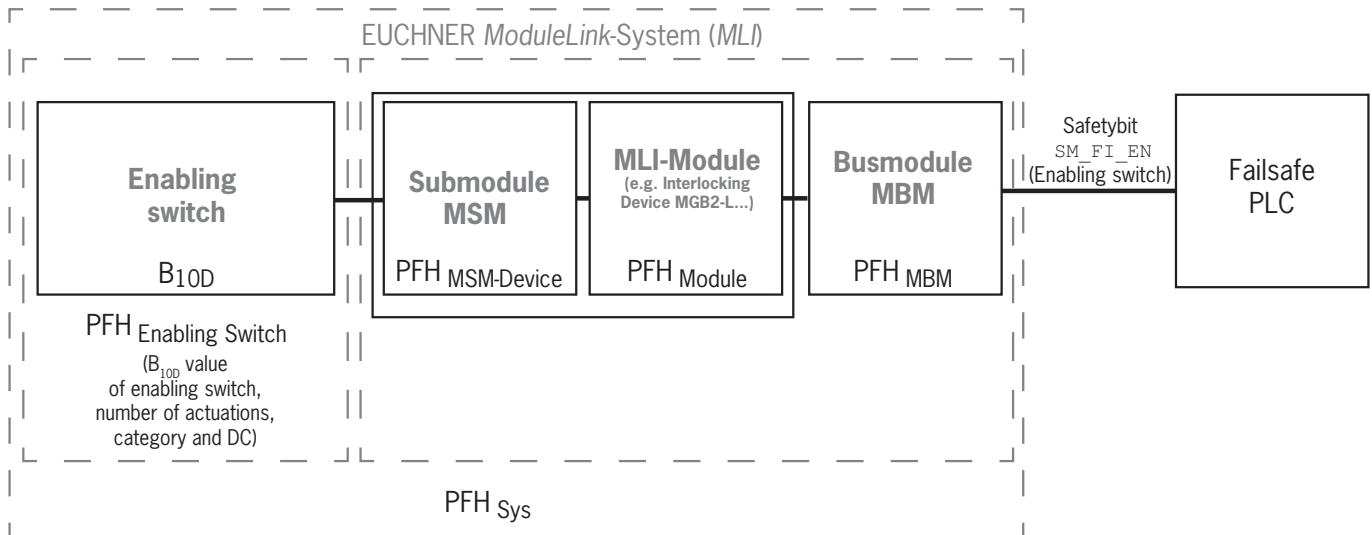
- › Safety function: evaluation of emergency stop
- › Safety characteristics: B_{10D} value of the emergency stop in the submodule (MSM) and PL, PFH, category and DC for the evaluation electronics (MLI modules) and the bus module (MBM)



3.3. Safety functions on submodules with enabling switch

Enabling function

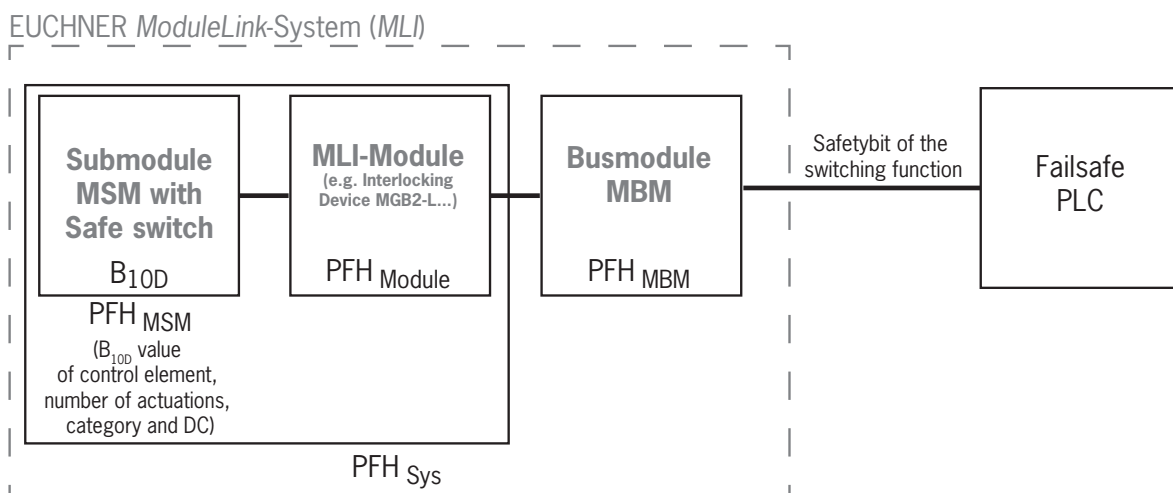
- › Safety function: evaluation of a connected enabling switch or other external electromechanical safety switches
- › Safety characteristics: B_{10D} value of the enabling switch (see operating instructions for the enabling switch) and PL, PFH for the evaluation electronics (MLI modules) and the bus module (MBM). The maximum PL, category and DC that can be achieved are determined by the values of the enabling switch (see operating instructions for the enabling switch).



3.4. Safety functions on submodules with safe pushbuttons and switches (general control elements, e.g. machine stop, test-pulse-monitored pushbutton, selector switch, key-operated rotary switch, acknowledgment button)

Detection of the switch position

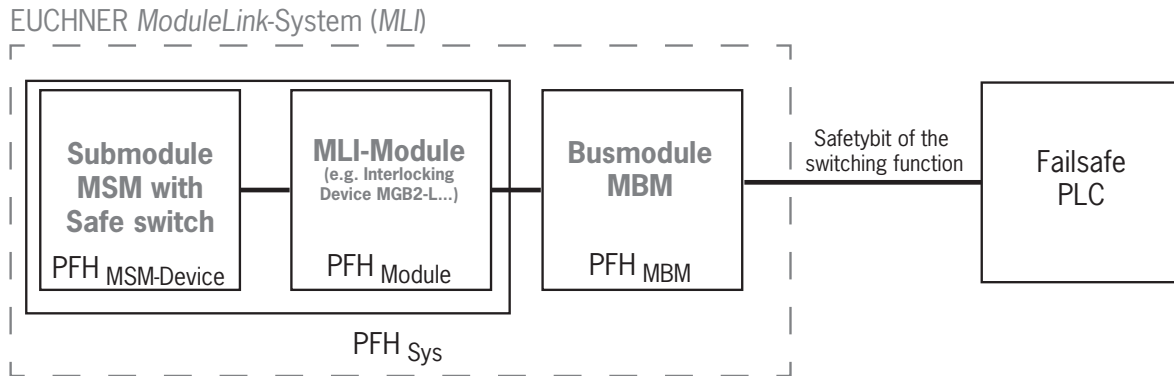
- › Safety function: evaluation of the switch position
- › Safety characteristics: B_{10D} value of the safe pushbutton or switch in the submodule (MSM) and PL, PFH for the evaluation electronics (MLI modules) and the bus module (MBM)
 - Category and DC depend on the evaluation and fault detection of the logic unit.
 - Evaluation in the MLI module will not detect mechanical faults without signal edge monitoring; category and DC are limited to cat. 3 and DC = 60%.
 - Mechanical faults must be excluded, e.g. by signal edge evaluation in the logic unit (PLC), to achieve cat. 4 and DC = 99%.
 - For safe control elements with edge monitoring in the MLI module (e.g. acknowledgment button), category and DC are determined by the evaluation unit (MLI modules).



3.5. Safety functions on submodules without B_{10D} (e.g. MSM-CKS2, MSM with operating mode selector)

Detection of the switch position

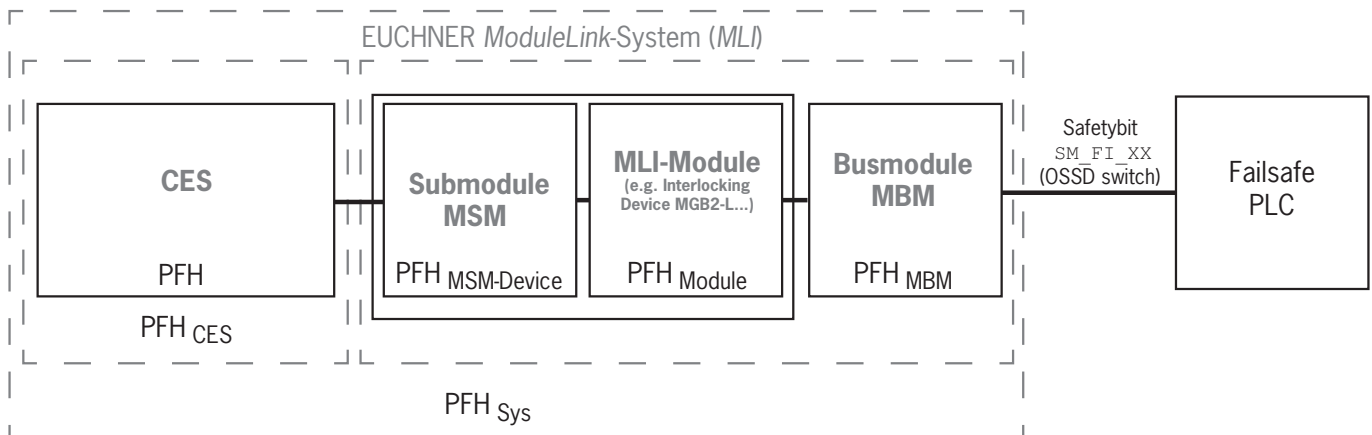
- › Safety function: evaluation of the switch position
- › Safety characteristics: PFH_{MSM-Device} value of the safe pushbutton or switch in the submodule (MSM) and PL, PFH for the evaluation electronics (MLI modules) and the bus module (MBM)



3.6. Safety functions on submodules with connection for OSSD safety switches

Detection of the switch position

- › Safety function: evaluation of the switch position
- › Safety characteristics: PFH value of the safety switch (see operating instructions for the safety switch), PFH_{MSM-Device} value of the submodule (MSM) and PL, PFH for the evaluation electronics (MLI modules) and the bus module (MBM)



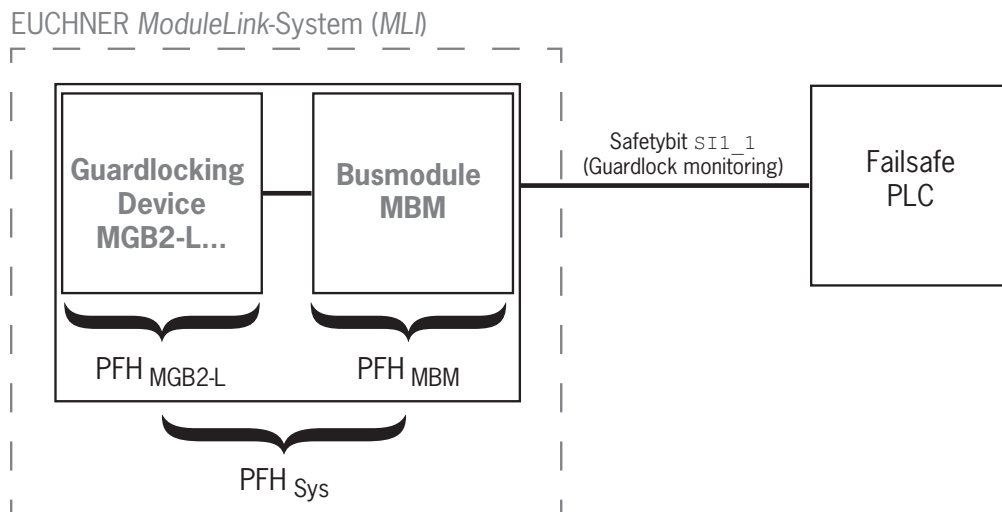
3.7. Determining safety characteristics of the overall system

The corresponding reliability values must be determined for each safety function in the overall system. Proceed as follows:

1. Refer to the data sheets or operating instructions for the system components containing the function for information on the reliability values for the related safety function.
2. Refer to the reliability value of the bus module MBM for the evaluation and forwarding of safety data.
3. Add together the values to a resulting reliability value PFH_{Sys} .

3.7.1. Calculation example for the “monitoring of guard locking” safety function

$$PFH_{Sys} = PFH_{MGB2-L} + PFH_{MBM}$$

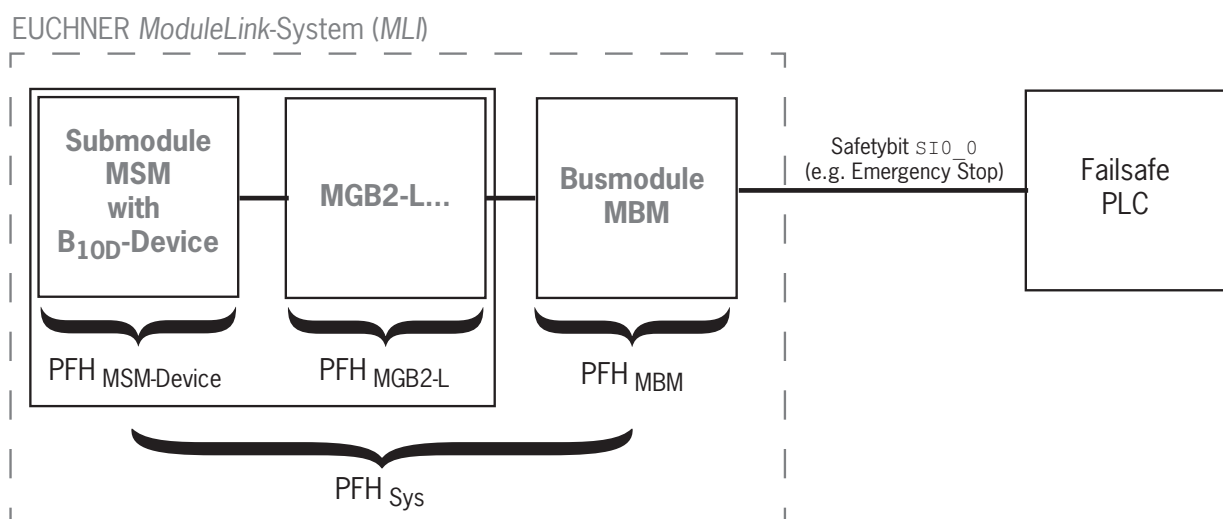


3.7.2. Calculation example for the “emergency stop” safety function

$$PFH_{Sys} = PFH_{MSM-Device} + PFH_{MGB2-L} + PFH_{MBM}$$

To calculate the $PFH_{MSM-Device}$ from the B_{10D} value, use the method in Annex C 4.2 of EN ISO 13849-1:2023.

The following applies: $PFH_{MSM-Device} = f(\text{category}_{MGB2}; DC_{MGB2}; B_{10D}; n_{op})$



4. Exclusion of liability and warranty

In case of failure to comply with the conditions for correct use stated above, or if the safety regulations are not followed, or if any servicing is not performed as required, liability will be excluded and the warranty void.

5. General safety precautions

Safety switches fulfill personnel protection functions. Incorrect installation or tampering can lead to fatal injuries to personnel.

Check the safe function of the safeguard and, if necessary, other safety functions particularly

- › after any setup work
- › after every replacement of a component relevant to safety (also after rotating a submodule)
- › after an extended period without use
- › after every fault
- › after any change to the DIP switch position
- › after every factory reset
- › after every firmware update.

Independent of these checks, the safe function of the guard should be checked at suitable intervals as part of the maintenance schedule.

	WARNING Danger to life due to improper installation or due to bypassing (tampering). Safety components fulfill a personnel protection function. › Safety components must not be bypassed, turned away, removed or otherwise rendered ineffective. On this topic pay attention in particular to the measures for reducing the possibility of bypassing according to EN ISO 14119:2025, section 8. › Mounting, electrical connection and setup only by authorized personnel possessing the following knowledge: - specialist knowledge in handling safety components - knowledge about the applicable EMC regulations - knowledge about the applicable regulations on operational safety and accident prevention.
	Important! Prior to use, read the operating instructions and keep these in a safe place. Ensure the operating instructions are always available during mounting, setup and servicing. You can download the operating instructions from www.euchner.com.

6. Function and system overview

An MLI system comprises at least the following components:

- › One bus module MBM
- › One module with MLI connection (e.g. interlocking or locking modules MGB2 or expansion modules MCM)

Modules can in turn contain submodules. *Fig. 1* shows a typical system layout with one bus module MBM (1), one locking module MGB2-L... (2) and the submodules MSM (3) installed in it. A full system can comprise up to 18 modules or submodules.

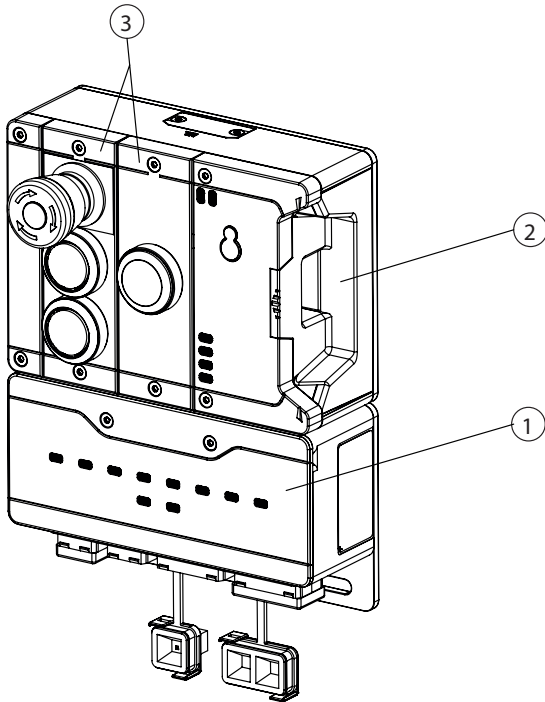


Fig. 1: Example system MGB2 Modular

6.1. Bus module MBM

Bus modules MBM have the following tasks:

- › Gateway to the bus connected
- › Central unit for control, evaluation and communication for the MLI modules connected
- › Central power supply for the MLI modules connected
- › IRT switch
- › Device web interface

6.2. Interlocking/locking module MGB2-I/MGB2-L

Together with a handle module, the interlocking module makes it possible to interlock movable guards. Together with a handle module, the locking module makes it possible to lock movable guards.

Interlocking/locking modules contain slots for submodules that provide additional functions.

For the exact functional description, refer to the operating instructions for your interlocking/locking module and the supplementary data sheets.

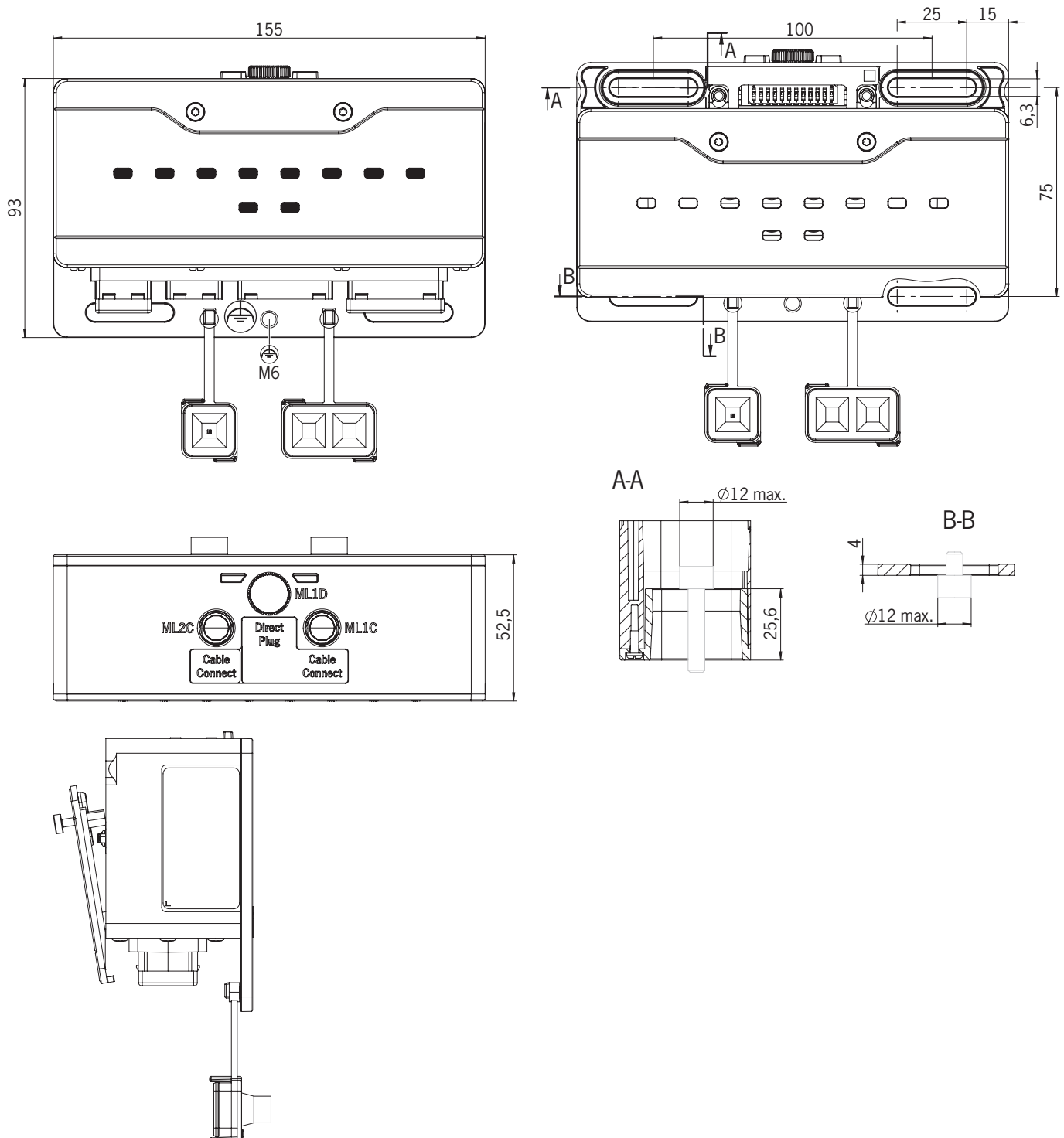
6.3. Expansion modules MCM

Expansion modules MCM have space for up to four submodules. In this way, even more extensive control tasks can be implemented.

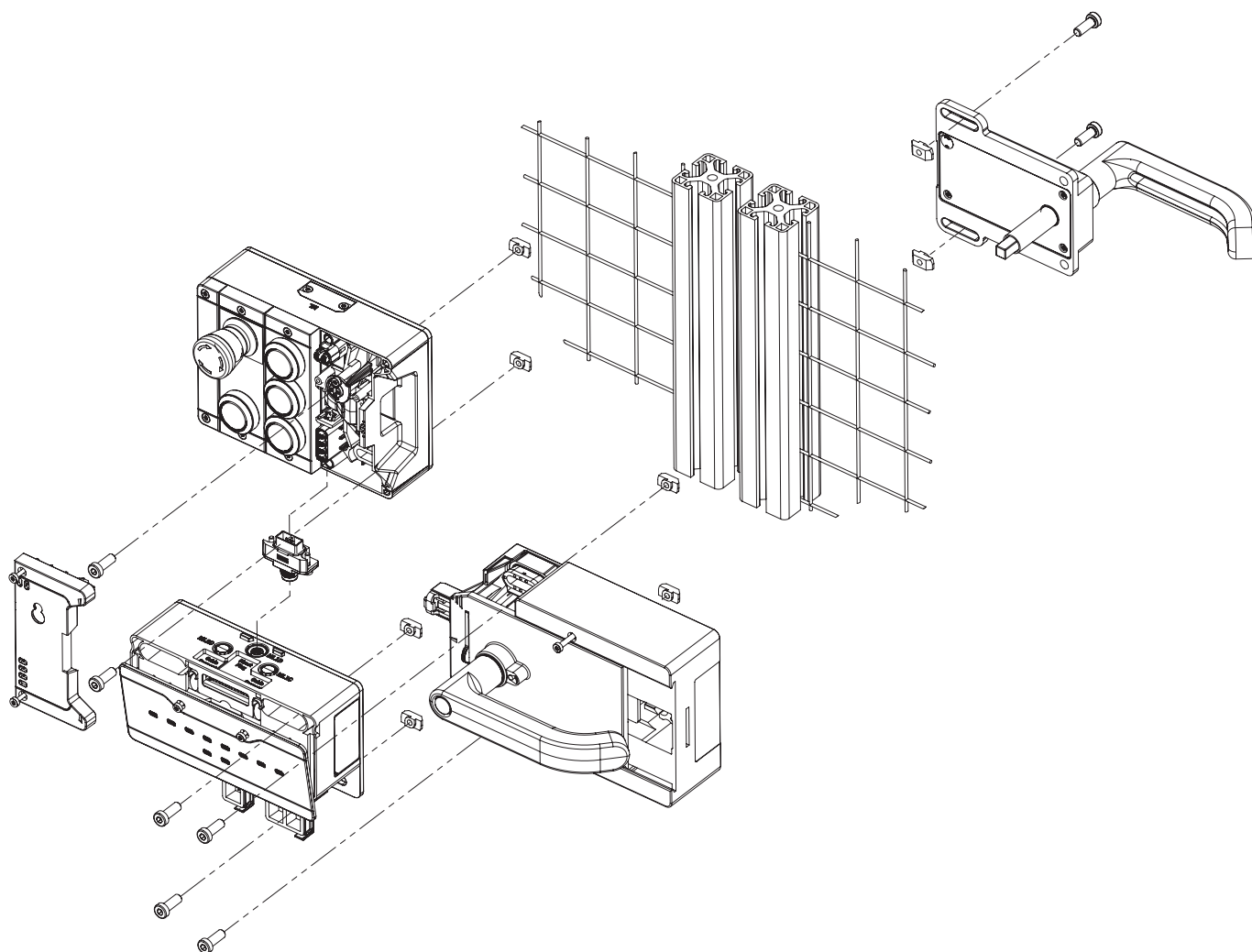
6.4. Submodules MSM

Submodules MSM can be installed in modules that have one or more submodule slots. Using the submodules, it is possible to install additional functions in the modules. Typical function expansions include emergency stop, pushbuttons, selector switches and indicators. For a detailed functional description, refer to the data sheet of the respective submodule.

6.5. Dimension drawing for bus module MBM



7. Mounting



8. Protection against environmental effects

A lasting and correct safety function requires that the system must be protected against foreign bodies such as swarf, sand, blasting shot, etc., which can become lodged in the housing.

Pay attention to the following measures:

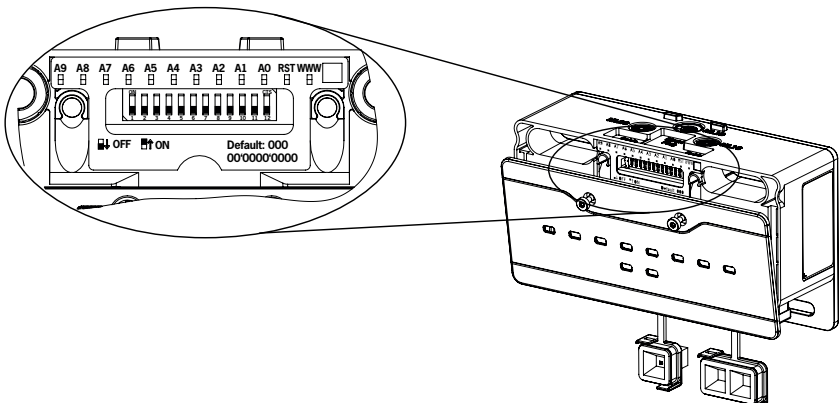
- › Seal unused connections using the covers provided.
- › Make sure the housing covers are correctly sealed and the cover screws are tightened to the necessary tightening torque.
- › Cover the device during painting work.

9. Controls and indicators

9.1. DIP switches

The DIP switches have the following functions:

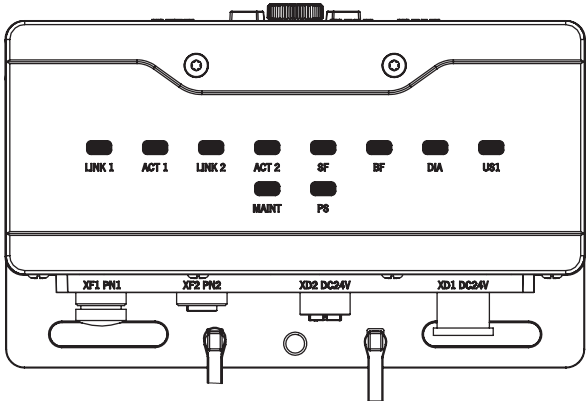
- › Setting the device's PROFI-safe address:
(PROFI-safe address via DIP switches ≠ 00000000000
PROFI-safe address type 2 = 00000000000)
- › Hardware reset to restore the device to the factory settings
- › Activating the device web interface



Switch	Description
A0 ... A9	Address switch, bits zero to nine For binary setting of the PROFI-safe address (PROFI-safe address type 2 factory setting: 0000000000)
RST	Factory reset (factory setting: off) For information on the factory reset, see chapter 13.3 on page 44.
WWW	Activating device web interface with extended diagnostic options. (factory setting: off) For information on the device web interface, see chapter 13.4 on page 45.

9.2. LED displays

The LEDs indicate the device status and the communication status.



LED	Description
Bus module MBM	
LINK 1	Connection correct: statically on PROFINET device localization: flashing Color: green
ACT 1	Connection setup: flashing Color: yellow Connection setup complete, cyclical data traffic: statically on Color: yellow
LINK 2	Connection correct: statically on PROFINET device localization: flashing Color: green
ACT 2	Connection setup: flashing Color: yellow Connection setup complete, cyclical data traffic: statically on Color: yellow
SF	System fault: statically on (see chapter 13. Diagnostics, troubleshooting and aids) Color: red
BF	Bus fault: statically on (see chapter 13. Diagnostics, troubleshooting and aids) Color: red
DIA	Indicates errors Color: red
US1	Power Up: flashing Normal state: statically on Color: green
MAINT	Indicates the error flashing code Color: red/green/yellow
PS	Normal state: statically on Device passivated: flashing Control system communication error: flashing Color: green

10. Electrical connection



WARNING

- In the event of a fault, loss of the safety function due to incorrect connection.
- › Mounting must be performed only by authorized personnel.
 - › Lay the connecting cables with protection to prevent the risk of short circuits.



CAUTION

- Risk of damage to equipment or malfunctions as a result of incorrect connection.
- › All electrical connections must either be isolated from the mains supply by a safety transformer according to EN IEC 61558-2-6 with limited output voltage in the event of a fault, or by other equivalent insulation measures.
 - › Metal plugs must be used for the power supply via push-pull plugs.
 - › Power devices which are a powerful source of interference must be installed in a separate location away from the input and output circuits for signal processing. The cable routing for safety circuits should be as far away as possible from the cables of the power circuits.
 - › To avoid EMC interference, follow the EMC notes on devices in the immediate vicinity of the system and its cables.
 - › To avoid EMC interference, the physical environmental and operating conditions at the installation site of the device must comply with the requirements according to the standard DIN EN 60204-1:2006, section 4.4.2/EMC.
 - › The functional earth  must be connected. A bore hole with M6 thread is provided on the mounting plate for this purpose.



Important!

- › The power supply for additional PROFINET devices may be forwarded via the bus module MBM. The total supply current through the system must not be higher than specified in the technical data.
- › The total current consumption of all connected modules and submodules (including MBM) must not exceed the value specified in the technical data. Refer to the technical data of the respective device for information about the current consumption of the individual modules and submodules.
- › If the bus module MBM does not appear to function after the application of the operating voltage (e.g. Power LED does not illuminate), the device must be returned unopened to the manufacturer.
- › To ensure the stated degree of protection is achieved, the cover screws must be tightened to a tightening torque of 1 Nm. Unused connections must be fitted with the covers provided.

10.1. Notes about UL



Important!

- › This device is intended to be used with a Class 2 power source in accordance with UL1310 ¹⁾. As an alternative an LV/C (Limited Voltage/Current) power source with the following properties can be used:
 - This device shall be used with a suitable isolating source in conjunction with a fuse in accordance with UL248. The fuse shall be rated max. 3.3 A and be installed in the max. 30 V DC power supply to the device in order to limit the available current to comply with the UL requirements.  Please note possibly lower connection ratings for your device (refer to the technical data).

1) Note on the scope of the UL approval: only for applications as per NFPA 79 (Industrial Machinery).
The devices have been tested as per the requirements of UL508 and CSA/ C22.2 no. 14 (protection against electric shock and fire).

10.2. Bus connections

The bus module MBM includes the PROFINET connections (XF1 and XF2) and the power supply connections (XD1 and XD2).

Depending on version, connection is via

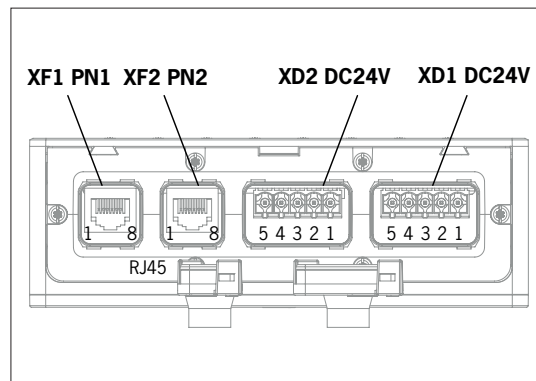
- push-pull plugs according to IEC 61076-3-117, variant 14
- 7/8" plugs and M12 plugs (D-coded) according to IEC 61076-2-101
- M12 plugs (L-coded), 5-pin, and M12 plugs (D-coded) acc. to IEC 61076-2-101
- M12 plugs (L-coded), 4-pin, and M12 plugs (D-coded) according to IEC 61076-2-101

The bus module MBM includes a PROFINET IRT switch for Ethernet connection.

10.2.1. Terminal assignment for version with push-pull plugs

Pin	Description
XF1.1	Receive Data RD+
XF1.2	Receive Data RD-
XF1.3	Transmit Data TD+
XF1.4	n.c.
XF1.5	n.c.
XF1.6	Transmit Data TD-
XF1.7	n.c.
XF1.8	n.c.
Functional earth on plug housing	

Pin	Description
XF2.1	Receive Data RD+
XF2.2	Receive Data RD-
XF2.3	Transmit Data TD+
XF2.4	n.c.
XF2.5	n.c.
XF2.6	Transmit Data TD-
XF2.7	n.c.
XF2.8	n.c.
Functional earth on plug housing	



Pin	Description
XD1.1	L1 operating voltage DC 24 V
XD1.2	N1 operating voltage 0 V
XD1.3	L2 auxiliary voltage ¹⁾ DC 24 V
XD1.4	N2 auxiliary voltage ¹⁾ 0 V
XD1.5	Functional earth ²⁾

Pin	Description
XD2.1	L1 operating voltage DC 24 V
XD2.2	N1 operating voltage 0 V
XD2.3	L2 auxiliary voltage ¹⁾ DC 24 V
XD2.4	N2 auxiliary voltage ¹⁾ 0 V
XD2.5	Functional earth ²⁾

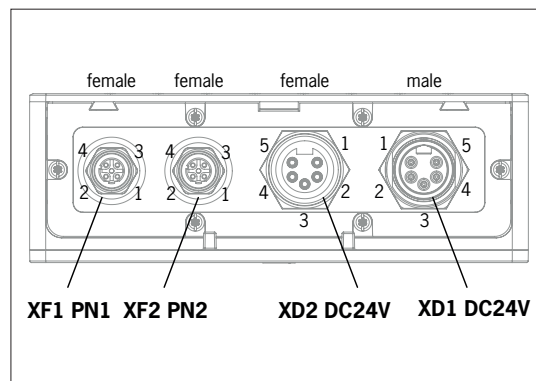
¹⁾ The auxiliary voltage is not required for the MGB2 system.

²⁾ Optional; we recommend using the FE connection on the mounting plate instead.

10.2.2. Terminal assignment for version with 7/8" and M12 plugs, D-coded

Pin	Description
XF1.1	Transmit Data +TD
XF1.2	Receive Data +RD
XF1.3	Transmit Data -TD_N
XF1.4	Receive Data -RD_N
Functional earth on plug housing	

Pin	Description
XF2.1	Transmit Data +TD
XF2.2	Receive Data +RD
XF2.3	Transmit Data -TD_N
XF2.4	Receive Data -RD_N
Functional earth on plug housing	



Pin	Description
XD1.1	N2 auxiliary voltage ¹⁾ 0 V
XD1.2	N1 operating voltage 0 V
XD1.3	Looped through
XD1.4	L1 operating voltage DC 24 V
XD1.5	L2 auxiliary voltage ¹⁾ DC 24 V

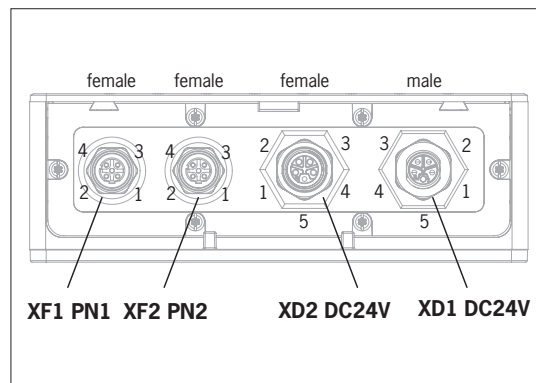
Pin	Description
XD2.1	N2 auxiliary voltage ¹⁾ 0 V
XD2.2	N1 operating voltage 0 V
XD2.3	Looped through
XD2.4	L1 operating voltage DC 24 V
XD2.5	L2 auxiliary voltage ¹⁾ DC 24 V

¹⁾ The auxiliary voltage is not required for the MGB2 system.

10.2.3. Terminal assignment for version with Power M12 plug (L-coded), 5-pin, and bus M12 plug (D-coded)

Pin	Description
XF1.1	Transmit Data +TD
XF1.2	Receive Data +RD
XF1.3	Transmit Data -TD_N
XF1.4	Receive Data -RD_N
Functional earth on plug housing	

Pin	Description
XF2.1	Transmit Data +TD
XF2.2	Receive Data +RD
XF2.3	Transmit Data -TD_N
XF2.4	Receive Data -RD_N
Functional earth on plug housing	



Pin	Description
XD1.1	L1 operating voltage DC 24 V
XD1.2	N2 auxiliary voltage ¹⁾ 0 V
XD1.3	N1 operating voltage 0 V
XD1.4	L2 auxiliary voltage ¹⁾ DC 24 V
XD1.5	Looped through

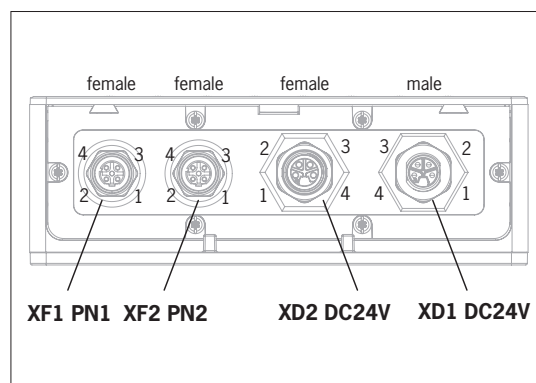
Pin	Description
XD2.1	L1 operating voltage DC 24 V
XD2.2	N2 auxiliary voltage ¹⁾ 0 V
XD2.3	N1 operating voltage 0 V
XD2.4	L2 auxiliary voltage ¹⁾ DC 24 V
XD2.5	Looped through

¹⁾ The auxiliary voltage is not required for the MGB2 system.

10.2.4. Terminal assignment for version with Power M12 plug (L-coded), 4-pin, and bus M12 plug (D-coded)

Pin	Description
XF1.1	Transmit Data +TD
XF1.2	Receive Data +RD
XF1.3	Transmit Data -TD_N
XF1.4	Receive Data -RD_N
Functional earth on plug housing	

Pin	Description
XF2.1	Transmit Data +TD
XF2.2	Receive Data +RD
XF2.3	Transmit Data -TD_N
XF2.4	Receive Data -RD_N
Functional earth on plug housing	



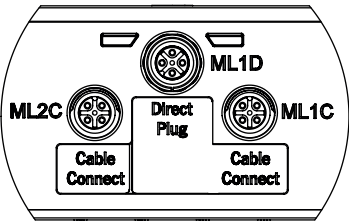
Pin	Description
XD1.1	L1 operating voltage DC 24 V
XD1.2	N2 auxiliary voltage ¹⁾ 0 V
XD1.3	N1 operating voltage 0 V
XD1.4	L2 auxiliary voltage ¹⁾ DC 24 V

Pin	Description
XD2.1	L1 operating voltage DC 24 V
XD2.2	N2 auxiliary voltage ¹⁾ 0 V
XD2.3	N1 operating voltage 0 V
XD2.4	L2 auxiliary voltage ¹⁾ DC 24 V

¹⁾ The auxiliary voltage is not required for the MGB2 system.

10.3. MLI connections

The MLI connections are used to connect modules to the bus module MBM. The sealing caps can be reordered (complete set AC-SET-BP-M12, order no. 156739).



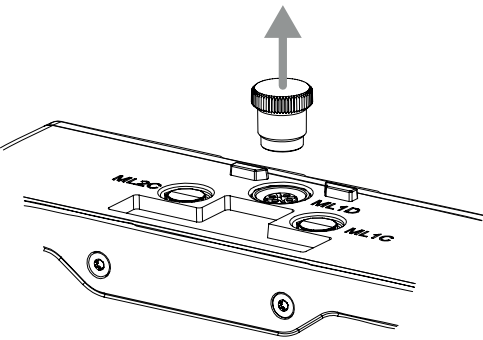
Connection	Description
ML1D (direct plug)	Module plug connector for direct mounting in a block. Important! Use only for direct mounting.
ML1C (cable connect)	Module plug connector for remote mounting (line 1).
ML2C (cable connect)	Module plug connector for remote mounting (line 2).

10.3.1. Direct mounting

Pay attention to the following points on direct mounting:

- › Ensure the modules are flush with each other. Excessively large distances will reduce the degree of protection achievable. Caution: The modules are only loosely connected together.
- › Make sure a sealing cap is fitted to unused connections.
- › Mount each module on the mounting surface as stipulated.

Before direct mounting, the sealing cap must be removed from connection ML1D (see figure below).

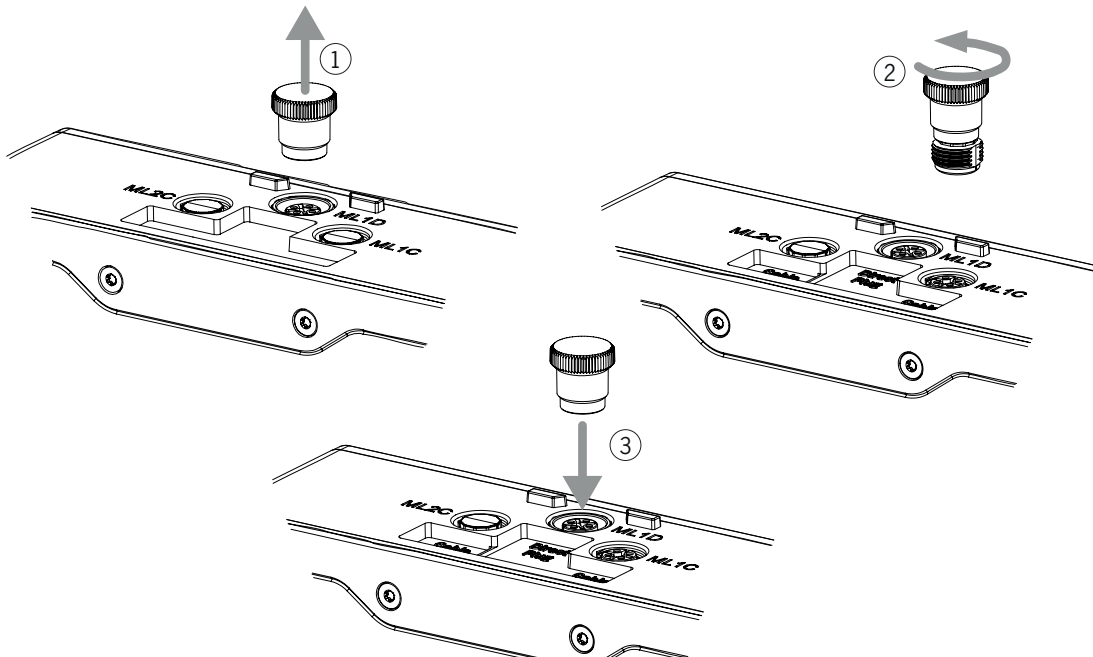


10.3.2. Remote mounting

Pay attention to the following points on remote mounting:

- › The maximum cable length for a line must not exceed 40 m.
- › Up to 3 basic modules can be operated per line. If you require a different configuration, contact our support team.
- › A maximum of 18 modules or submodules can be operated on one bus module MBM. Submodules count as one module here. Attention is to be paid to the maximum permissible total current consumption (see 15. *Technical data*).
- › The number of safe devices in an overall system is limited to 12.
- › Always use the module plug connector ML1C, ML2C or both for remote mounting.
- › Lay the cable so that it is protected against damage as far as possible.
- › Make sure a sealing cap is fitted to unused connections.
- › Make sure the connecting cables are correctly screwed into place to achieve the stated degree of protection.

Before remote mounting, the sealing cap must be unscrewed from connection ML1C. The sealing cap for connection ML1D is used as a tool for this purpose (see figure below). On the use of a second line, the sealing cap for ML2C must also be unscrewed. Then the sealing cap for connection ML1D must be re-fitted.



10.4. Connecting modules

Modules can either be connected together directly or using cables (see Fig. 2: Connecting modules).

Each module has a top and a bottom connection. You can use either the bottom or the top connection or both if the module is between two other modules.

The bottom module connector is already integrated. To use the top connection, change its position. If you want to use both connections, you must order a corresponding module connector. Use only the module connectors intended to interconnect the modules (see Table 2: Overview of module connectors). The maximum cable length for a line must not exceed 40 m.

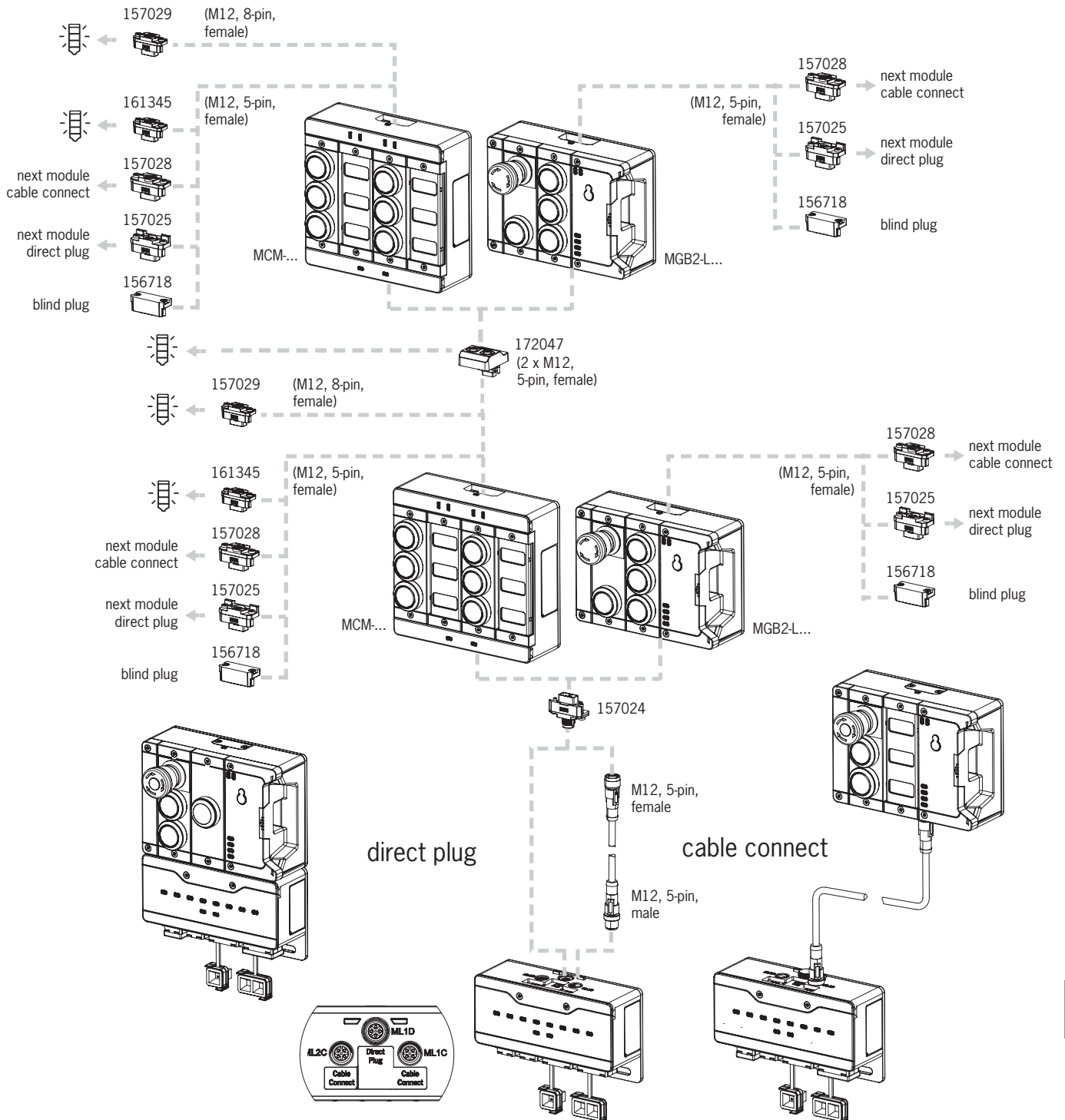


Fig. 2: Connecting modules

Table 2: Overview of module connectors

Function	Order no.	Included?
Module connector M12, 5-pin plug	157024	1x *
Blanking cover	156718	1x *
Set with sealing caps for unused connections	156739	Yes
Module connector, 5-pin socket, for the direct connection of a further module	157025	No, must be ordered separately
Module connector M12, 5-pin socket, for the connection of a further module via a connecting cable	157028	
Module connector 2 x M12, 5-pin socket, for the connection of a further module and a stacklight via connecting cables**	172047	
Module connector M12, 5-pin socket, for the connection of a stacklight**	161345	
Module connector M12, 8-pin socket, for the connection of a stacklight**	157029	
Connecting cable M12, 5-pin	See catalog or www.euchner.com	
Connecting cable M12, 8-pin		

* Not for MGB2-...-Y0000-...
** Only for MCM-MLI-...JJ-..

11. Setup

A typical MLI system usually consists of several modules and submodules. Which modules and submodules are used is determined by the bus module MBM on each system start.

To suit this configuration, in the configuration software for your control system, you must assemble the related data blocks for the communication data for the individual modules and submodules and, if necessary, set parameters. The individual modules and submodules are already included in the GSD file and must be applied in the planning software (e.g. TIA-Portal from SIEMENS) to suit your system layout. You will find an overview of the communication data in chapter 11.2. *Overview of the communication data.*

You will find an overview of the parameters that can be set for modules/submodules in chapter 11.9. *Configuring and setting parameters for modules and submodules on page 33.*

Some data blocks are permanently linked to the related module or submodule; you can add others optionally (see chapter 11.4. *System layout and layout of the data areas in the control system*).

You can find which data blocks your modules or submodules contain on the data sheet for the respective device (see chapter 11.3. *Information on the related data sheets*).

In chapter 11.4. *System layout and layout of the data areas in the control system on page 27* , it is explained how the communication data for a system are assembled.

From chapter 11.7. *Integrating into PROFINET and PROFIsafe on page 30* , it is explained how you configure and set the parameters for the individual modules and submodules in the configuration software for your control system.

11.1. Teach-in operation

The modules and submodules must be assigned to each other using a teach-in function before the system forms a functional unit.

During the teach-in operation, the module is in the safe state (all safe bits are not set).



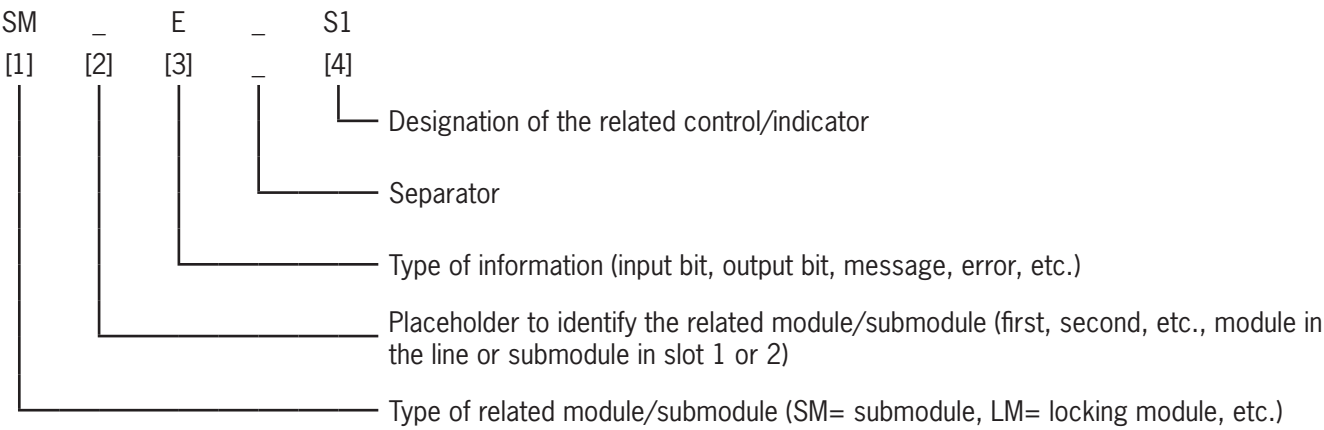
Important!

- A system that has not yet been taught-in remains in teach-in standby until all modules have been taught-in during a power-up process. Systems that have already been taught-in must be reset to the factory setting in order to restore teach-in standby.
- Faulty modules or submodules can be replaced with identical modules or submodules without a teach-in operation.

11.2. Overview of the communication data

The associated input and output bits are listed on the data sheet for the respective module/submodule (see chapter 11.3. *Information on the related data sheets*). The bit identifiers always have the same structure (see below).

The following example shows an error status bit [E] in a submodule [SM] for the switch position S1 [S1].



The individual abbreviations are explained in the following tables. You will find a detailed explanation of the individual bits on

Bit identifiers for position [1]	Description
BM	Data from bus modules MBM
LM	Data from interlocking/locking modules MGB2-I.../MGB2-L...
SM	Data from submodules MSM
EM	Data from expansion modules MCM

Bit identifiers for position [4]	Description
S	Switch 1, 2, ...
H	Lamp 1, 2, ...
ES	Emergency stop
SK	Safe signal "Position of the bolt tongue" (guard closed and bolt tongue inserted)
UK	Safe signal "Position of guard locking"
CL	Guard locking control
EN	Enabling switch
SYS	System
ER	Escape release
ML	Module connection (MLI)
SM	Submodule

Datenblatt / Data Sheet MGB2-L1-MLI-U-Y0000-BJ-136776

MGB2-L2-MLI-U-Y0000-BJ-156392
MGB2-L1-MLI-M-Y0000-BJ-158698
MGB2-L2-MLI-M-Y0000-BJ-158711

EUCHNER

Made in Germany • Dimensions in mm

no responsibility is accepted for the accuracy of the information. © EUCHEC GmbH • CO, NG

Technical drawing of the MGB2-L1-MLI-U-Y0000-BJ-136776 device. It shows a rectangular component with two main slots labeled 'SLOT 1' and 'SLOT 2'. Pin 'X1' is located at the bottom, and pin 'X2' is at the top. The device has a complex internal structure with various components and wiring.

Betriebsanleitung beachten
for operation please read the Data Sheet and the instruction manual.
Please observe the operating instructions
in case of a replacement before and after and operating instructions, the information of the data sheet are to be considered.

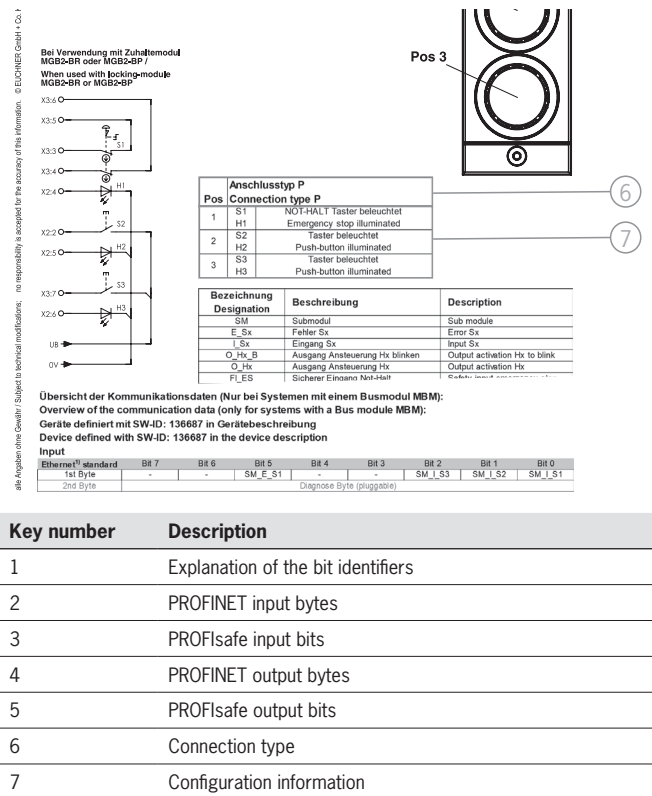
Bezeichnung Designation	Beschreibung Description
LM	Zufahrtsmodul Locking module
E_G	Fehler generell Error generally
E_ER	Fehler Fluchtenfrüherung Error escape release
E_SM1	Fehler Submodul 1 Error sub module 1
E_SM0	Fehler Submodul 0 Error sub module 0
LUK	Eingang UK Input UK
LUK	Eingang UK Input UK
D_RUN	Diagnose Runmode Diagnostic runmode
LOL	Stellung Zuführung Locking position
LOT	Stellung Regel Tongue position
LOD	Stellung Tür Door position
FI_UK	Sicherer Eingang UK Failsafe input UK
FI_UK	Sicherer Eingang UK Failsafe input UK
ACK_G	Fehlerquellierung generell Acknowledgement generally
ACK_ER	Flechterquellierung Acknowledgement escape release
O_CL	Ausgang Output locking control
FO_CL	Zuführungsanspeuerung Failsafe output locking-control

Übersicht der Kommunikationsdaten (Nur bei Systemen mit einem Busmodul MBM):

Overview of the communication data (Only for systems with a Bus module MBM):

Input		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Ethernet ¹⁾ standard	1st Byte	LM_E_G	LM_E_ER	LM_E_SM1	LM_E_SM0	-	LM_I_LUK	LM_I_SK	LM_O_RUN
	2nd Byte	-	-	-	-	-	LM_I_LOL	LM_I_OD	LM_I_OD
Diagnose Byte (Diagnoseable)									
Ethernet ¹⁾ SAFE		2nd Byte							
		LM_FL_LUK LM_FL_SK							
Output		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Ethernet ¹⁾ standard	1st Byte	LM_ACK_G	LM_ACK_ER	-	-	-	-	-	LM_O_CL
	2nd Byte	-	-	-	-	-	-	-	-
Ethernet ¹⁾ SAFE		1st Byte							
		LM_FO_CL							

¹⁾ Ethernet Protokoll in Abhängigkeit des verwendeten MBM Busmoduls / Ethernet protocol according to the used MBM Busmodule



26 (translation of the original operating instructions) MAN20001743-04-08/26

11.4. System layout and layout of the data areas in the control system

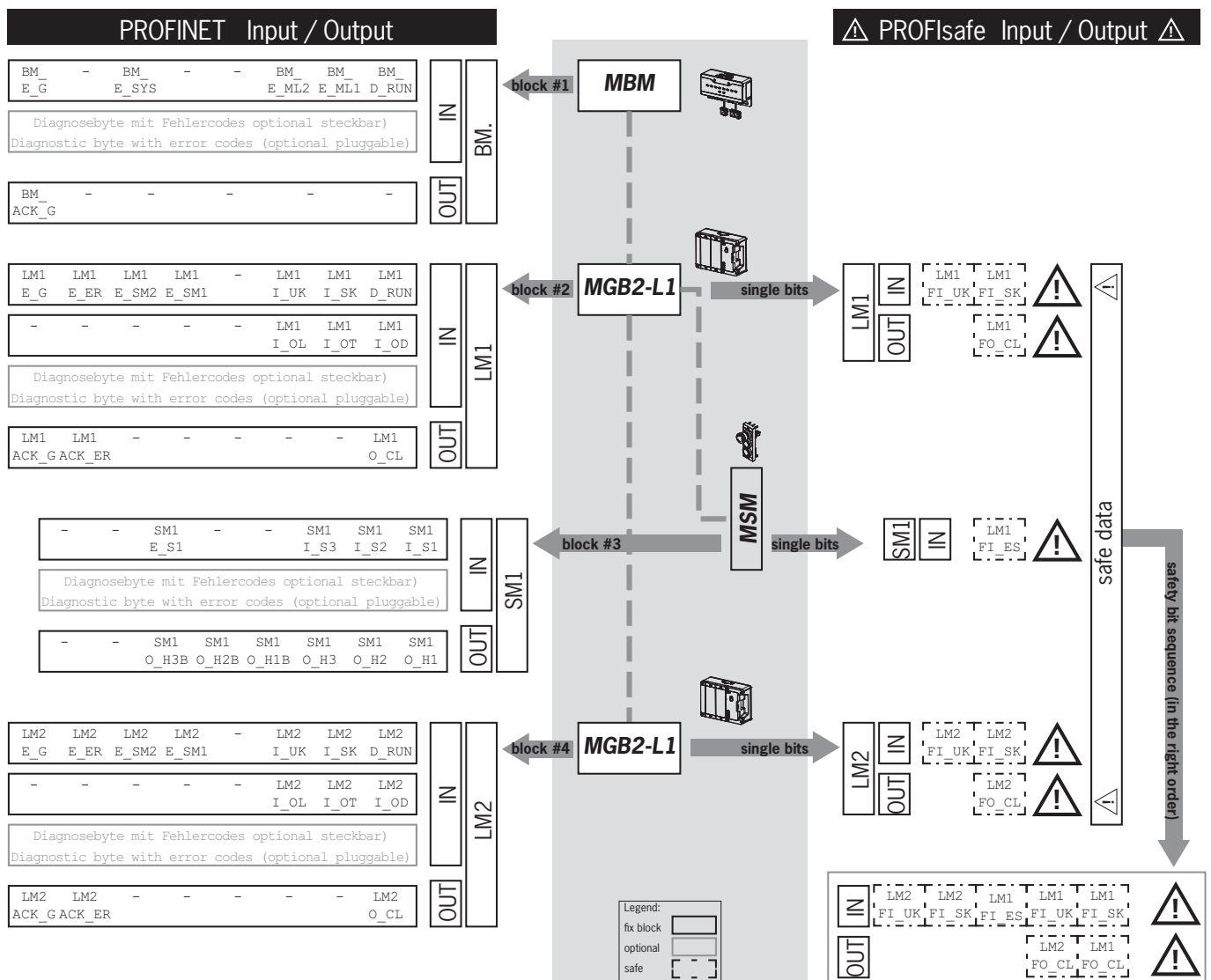
Due to its modular layout, the MLI system offers you a very large degree of flexibility. This flexibility also applies to the use of the communication data. The data areas that the system occupies in your control system are dependent on your system layout.

Every module has fixed communication data that are permanently assigned when the modules are combined in the configuration software for your control system. For some modules and submodules, there are also optional data that you can evaluate. These can be more detailed diagnostic functions, for example.

The following graphic is intended to make it clear which rules must be used to combine the data blocks from the individual modules and submodules. Here a differentiation is made between non-safe PROFINET data and safe PROFIsafe data.

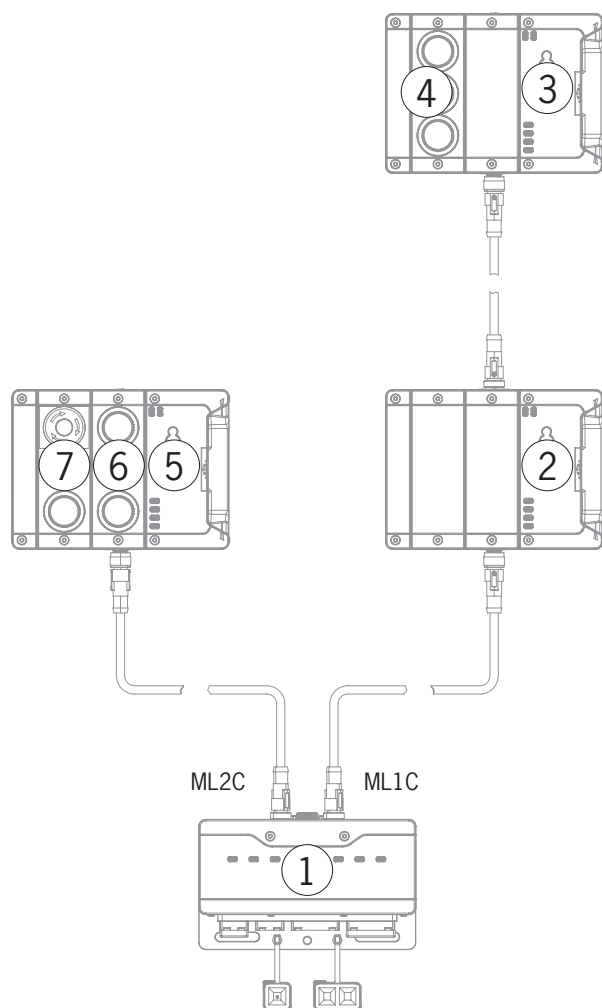
While PROFINET data are always incorporated by bytes ("block #1 ... #4"), the data are always incorporated by individual bits for PROFIsafe data ("single bits" in the figure below). This means you must make sure you provide enough safe memory for PROFIsafe data.

The following example shows a typical system layout with the bus module (BM1) to which two locking modules (LM1 and LM2) are connected on one line. The first locking module (LM1) also contains a submodule (SM1) with one emergency stop and two pushbuttons. Based on this example, you can see the composition of the communication data.



The individual data blocks or bits are always combined in the same sequence as the system layout. Here the counting is always started at the bus module (1) and then continued from the first to the last modules on a line. If there are two lines, the complete first line on ML1C (2...4 in the figure below) is counted first and then the complete second line on ML2C (5...7 in the figure below). Submodules in a module are counted immediately after the module in which they are inserted before the count continues with the next module. For submodules, the SLOT number defines the sequence.

The following figure is intended to clarify the counting sequence. In chapter 11.9. *Configuring and setting parameters for modules and submodules on page 33*, it is explained in detail how this aspect functions.



11.5. PROFINET data bytes

Each module or submodule sends specific, non-safe communication data. The following chapters provide an overview of the most important module types and their data. You can find item-specific information on which data blocks your modules or submodules contain on the supplementary data sheet (see chapter 11.3. *Information on the related data sheets*).

The following modules can be present in various combinations in an MLI system:

- A bus module MBM (contains everything necessary for a bus connection).
- Several interlocking/locking modules, MGB2-I or MGB2-L (together with the handle module, they form an interlocking device with or without guard locking).
- Several expansion modules MCM
- Several submodules MSM.

Each module or submodule occupies a certain number of PROFINET data bytes in the input and output areas of the control system.

With some modules and submodules, you have the choice between a **standard configuration (basic)** that has basic status, signaling and control functions or an **extended configuration** that also contains an additional byte with exact error codes for diagnostic purposes.

11.6. PROFIsafe data bytes

Safe PROFIsafe data are transmitted in addition to the non-safe PROFINET data. These data include all information on the position of the bolt tongue and guard locking on an interlocking or locking module MGB2, emergency stop and enabling switch, for example.

While PROFINET data are always incorporated by bytes, the data for PROFIsafe are always incorporated by individual bits. This means you must make sure you provide enough safe memory for PROFIsafe data.

The following PROFIsafe data blocks are provided:

- 2 input bytes and 2 output bytes
- 4 input bytes and 4 output bytes
- 8 input bytes and 8 output bytes

4 bytes of PROFIsafe internal data are always appended to these device-specific data blocks.

The bus module supports PROFIsafe version 2.6.1 as standard. If your control system does not support this version, the respective modules for version 2.4 are also available from us under “Legacy” in the GSD.

All device-specific data bits are present in parallel in the non-safe PROFINET data area and can be used as status bits there.

	Important! Never use the status bits for safety functions!
---	--

11.6.1. Data block for PROFIsafe

	Important! For the scope of the safe bits, refer to the associated data sheet for your device or set. Use only bits that are specified according to the data sheet. Safe bits are marked there with a warning symbol and bounded with a dotted line.
---	--

11.7. Integrating into PROFINET and PROFIsafe

	NOTICE The parameters “Update time” and “F-WD-Time” have a decisive effect on the reaction time of the safety function. The safety function could be lost if the reaction times are too long. You will find a list of all parameters that can be set in chapter 11.9.2 on page 37.
	Important! You will require the corresponding GSD file in GSDML format to integrate the system: ▸ GSDML-Vx.x-EUCHNER-MBM_XXXXXX_TXX-YYYYMMDD.xml You will find the GSD file in the download area at www.euchner.com. Always use the latest GSD file. For new configuration, please use the GSD file GSDML-V2.44-EUCHNER-MBM-IRT_2512512-20260817.xml or a newer version. The GSD file does not necessarily have to be updated on replacement. However, all of the newer functions might not be available in this case. Prior to setup, the GSD file must be imported into the configuration software for the control system (see 11.7. Integrating into PROFINET and PROFIsafe on page 30 and the control system manual). In the download area, you will find application examples in which integration into different system environments is described.

You must perform the following steps to integrate the system into PROFINET:

1. Configure the system with the configuration software for the control system and set the parameters.

The following PROFINET parameters must be set in the bus module parameters:

- Device name (factory setting from GSD file): *[EUCHNER-MBM]*.
- IP address: optionally fixed or dynamic
- Update time:
recommendation [automatic]

The following PROFIsafe parameters must be set in the bus module parameters:

- F_Dest_Add (PROFIsafe address)
- F_WD_Time (time during which the control system expects a response from the PROFIsafe device): [xxx ms]. Default value from GSD file: [600 ms].

2. Setting Profisafe address:

From V2.3.X, the MBM supports the PROFIsafe address via DIP switches and address type 2. The type is selected using the DIP switches (see chapter 11.8. PROFIsafe address type on page 31).

PROFIsafe address via DIP switches:

- Set F_Dest_Add using the DIP switches on the bus module MBM

PROFIsafe address type 2:

- Set DIP switches on the bus module MBM to 000000000001
- Change to SETTINGS via the device web interface (13.4.1. Using device web interface on page 45) of the MBM
- Enter F_Dest_Add
- Enter F_Source_Add
- Save using the “Save Addresses” button
- The device is restarted automatically (NOTICE: interruption of the PROFINET connection)

3. Identical addresses must be set in the control system and on the device.
4. If necessary, set additional parameters for the individual modules. You will find an overview of the possible parameters in chapter 11.9.2. List of the parameters that can be set per module/submodule on page 37.
5. Save the configuration and transfer it to the system.

11.8. PROFIsafe address type

From V2.3.X, the bus module MBM can also be used with PROFIsafe address type 2. Whenever possible, use address type 2 for new projects.

Changing the addresses requires a factory reset.



NOTICE

- › Use only one address type within a network.
- › Use address type 2 if more than one safe PLC is used in the network.
- › When replacing an old device with a new one (from V2.3.X), enter the F-source address and the F-destination address via the web server.
- › More than 1,022 addresses are possible only with a new GSDML file (from date code 20260817).

PROFIsafe address via DIP switches

For this address type, the DIP switches are used to assign the F-destination address (F_Dest_Add). It is not possible to configure the address via the web server. However, the assigned address is displayed via the web server for information purposes. As the bus module MBM also expects the F-source address (F_Source_Add), this address is automatically applied by the PLC and saved during initial setup.

If the PLC’s address (F_Source_Add) does not change, the F-destination address (F_Dest_Add) of the bus module MBM can still be changed via the DIP switches without a factory reset. If the F-source address (F_Source_Add) deviates from the address during initial setup, the bus module MBM automatically reports an error. A factory reset is required.

Example:

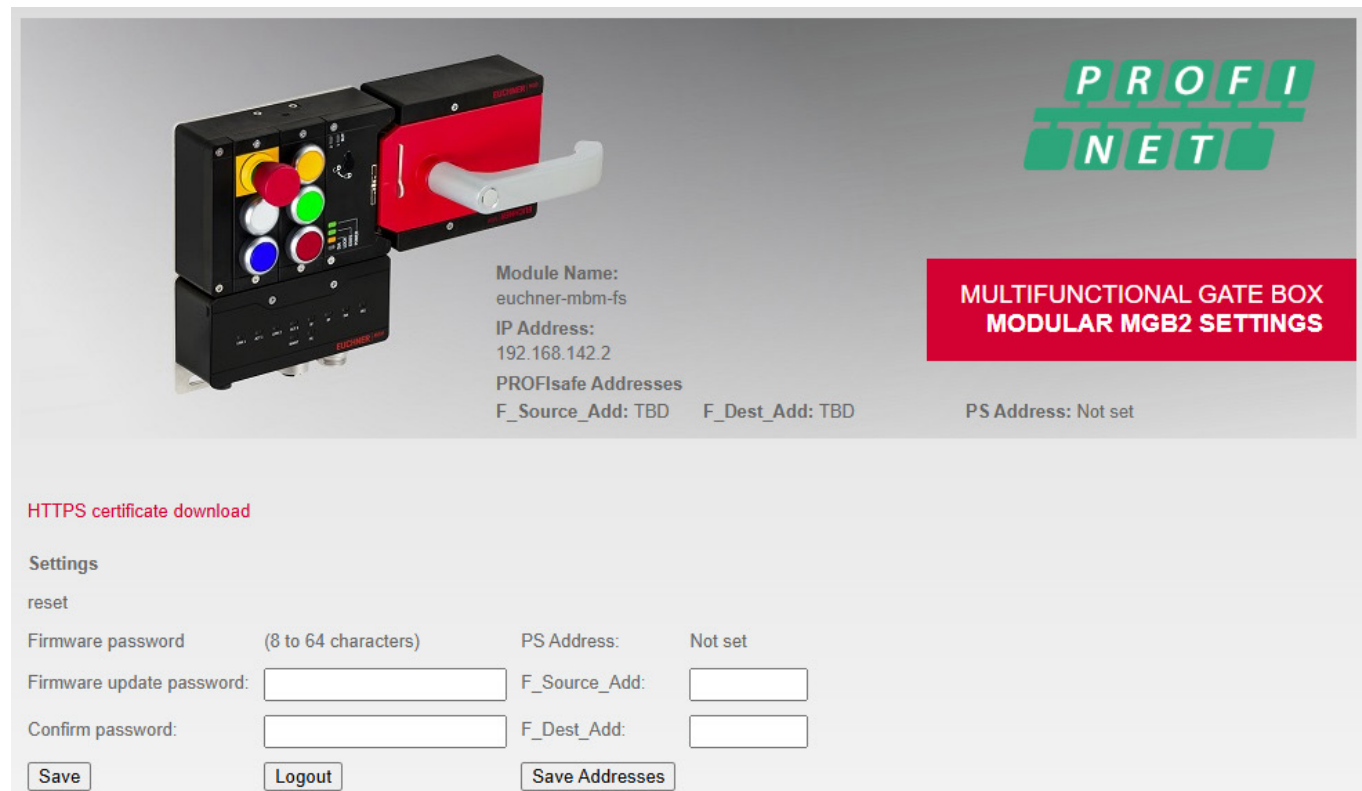
Switch	Description
A0 ... A9	Address switch, bits zero to nine For binary setting of the PROFIsafe address (factory setting: 0000000000)
RST	Factory reset (factory setting: off)
WWW	Activating device web interface with extended diagnostic options. (factory setting: off)

The following DIP switch setting results from F_Dest_Add 12:

Switch	A9	A8	A7	A6	A5	A4	A3	A2	A1	A0
DIP switch position MBM	off	off	off	off	off	off	on	on	off	off
Significance	2 ⁹	2 ⁸	2 ⁷	2 ⁶	2 ⁵	2 ⁴	2 ³	2 ²	2 ¹	2 ⁰
Decimal value	512	256	128	64	32	16	8	4	2	1

PROFIsafe address type 2 via web server

For this address type, the F-source address and the F-destination address must be assigned via the web server of the bus module MBM. The web server must be activated via DIP switches. The DIP switches of the F-address must remain set to 0 and must not be changed (DIP switches to 000000000001). The respective permissible values are 1 to 65534. The address assignments must be set once during setup. The values are saved and are retained after a voltage reset. The addresses can be changed via a reset using the web server. Alternatively, a factory reset can also be performed using the DIP switch.



PROFI
NET

**MULTIFUNCTIONAL GATE BOX
MODULAR MGB2 SETTINGS**

Module Name:
euchner-mbm-fs
IP Address:
192.168.142.2
PROFIsafe Addresses
F_Source_Add: TBD F_Dest_Add: TBD PS Address: Not set

HTTPS certificate download

Settings
reset

Firmware password (8 to 64 characters) PS Address: Not set

Firmware update password: F_Source_Add:

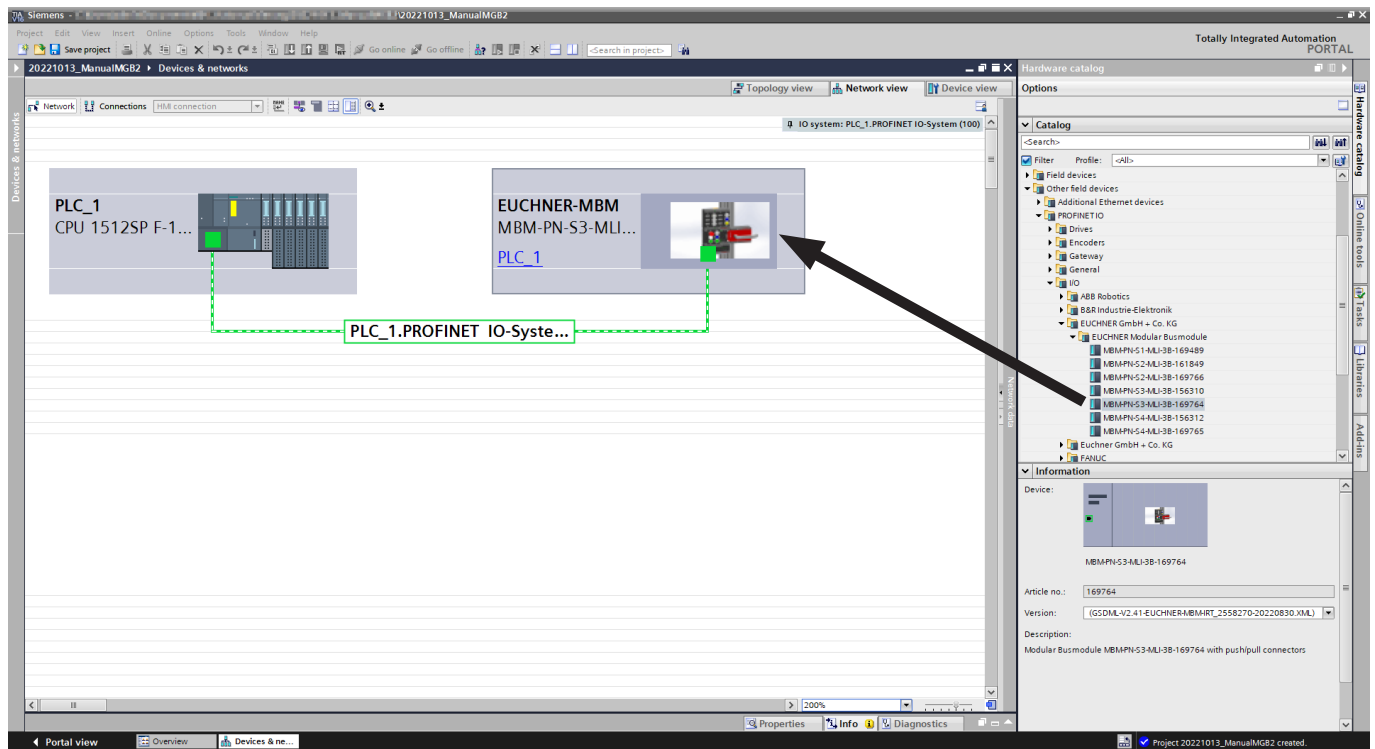
Confirm password: F_Dest_Add:

11.9. Configuring and setting parameters for modules and submodules

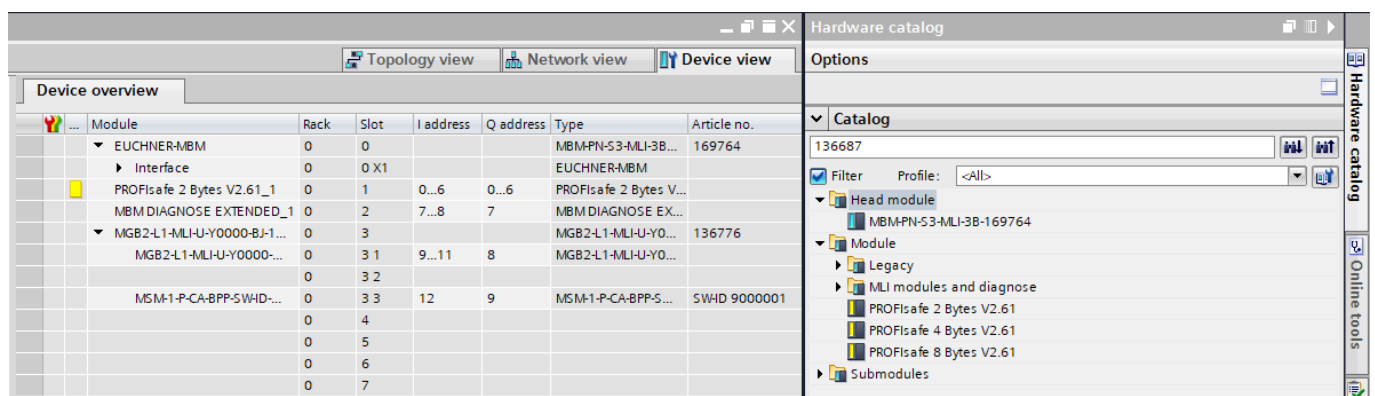
To be able to use the individual modules and submodules, these must be configured and the parameters set correspondingly in the configuration software for your control system. The following chapters describe these steps based on the example of the configuration software TIA-Portal from SIEMENS.

11.9.1. Combining modules and submodules

To be able to perform the following steps, first the bus module MBM must be dragged from the hardware catalog to the network overview.



Here, the MBM forms the head module.



Drag a corresponding PROFIsafe data module to SLOT1. If STEP 7 v5.5 SP4 is used, PROFIsafe x Bytes V2.4 must be selected under "Legacy". It must be large enough that there is space for the individual safe data bits for the modules/submodules in your system. On this topic, see also chapter 11.4. *System layout and layout of the data areas in the control system on page 27.*

The screenshot shows the HW Config software interface. On the right, the 'Hardware catalog' window is open, displaying a list of modules. The 'Legacy' section is expanded, showing various 'PROFIsafe' modules. Three modules are highlighted with a red box: 'PROFIsafe 2 Bytes V2.61', 'PROFIsafe 4 Bytes V2.61', and 'PROFIsafe 8 Bytes V2.61'. On the left, the 'Device overview' window shows a table of installed modules. The 'PROFIsafe 2 Bytes V2.61_1' module is highlighted with a red box. An arrow points from the highlighted modules in the catalog to the highlighted module in the device overview.

Module	Rack	Slot	I address	Q address	Type	Article no.
EUCHNER-MBM	0	0			MBM-PN-53-MLI-3B...	169764
Interface	0	0 X1			EUCHNER-MBM	
PROFIsafe 2 Bytes V2.61_1	0	1	0...6	0...6	PROFIsafe 2 Bytes V...	
MBM DIAGNOSE EXTENDED_1	0	2	7...8	7	MBM DIAGNOSE EX...	
MGB2-L1-MLI-U-Y0000-BJ-1...	0	3			MGB2-L1-MLI-U-YO...	136776
MGB2-L1-MLI-U-Y0000-...	0	3 1	9...11	8	MGB2-L1-MLI-U-YO...	
	0	3 2				
MSM-1-P-CA-BPP-SWHD-...	0	3 3	12	9	MSM-1-P-CA-BPP-S...	SWHD 9000001
	0	4				
	0	5				

All other modules and submodules must be combined from the hardware catalog such that all devices can be seen in the correct sequence in the device overview. First create an exact representation of your system.

The individual modules are listed in the hardware catalog with order number and item designation. The submodules are listed with the software ID (SW-ID).

You will find this information on the type labels on the modules/submodules (see also chapter 11.4 on page 27).

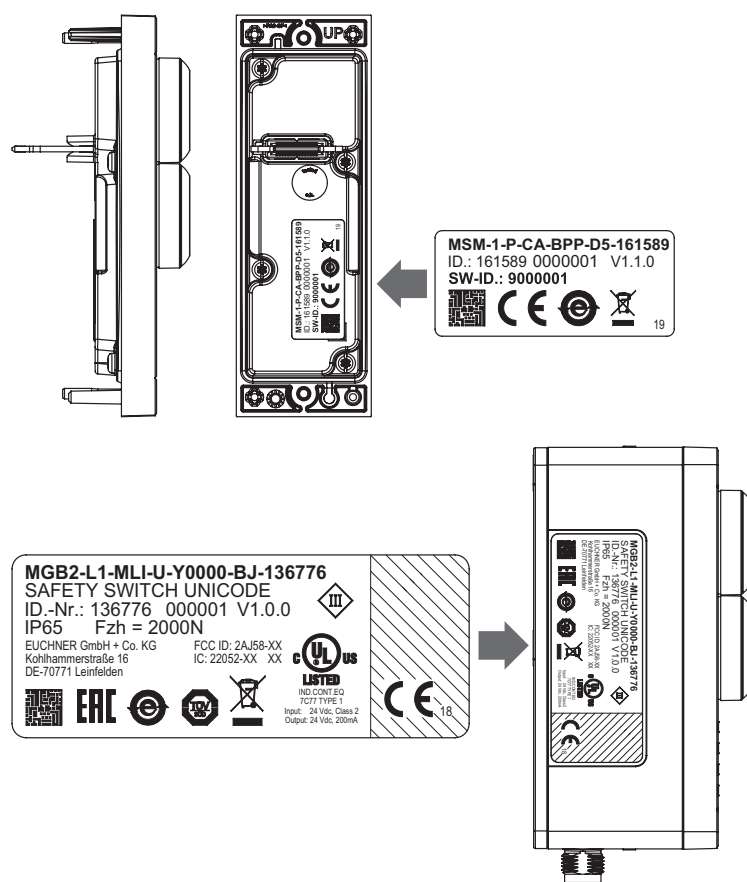


Fig. 4: Type labels on the modules/submodules (using MSM and MGB2 as examples)

Factory-equipped devices include an additional type label on the module. This label contains the SW IDs of the submodules in the module.

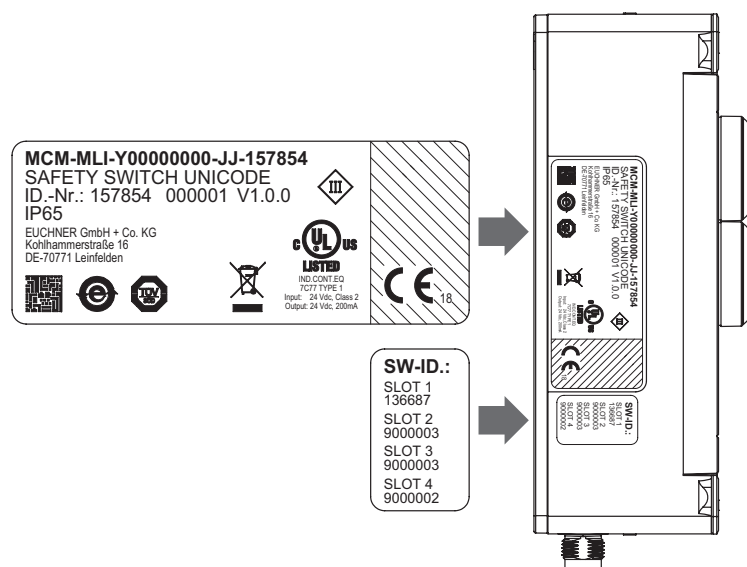


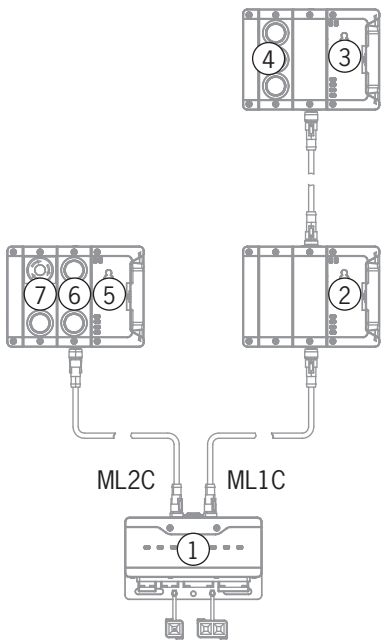
Fig. 5: Type labels on devices factory-equipped with submodules (using MCM as an example)

The figure below shows an example system layout.



NOTICE

If there are slots without a function (e.g. with blanking cover), the corresponding slots in TIA must also remain empty.



Module	Rack	Slot	I address	Q address	Type	Arti...
1 EUCHNER-MBM	0	0			MBM-PN-S3-MLI-3B-1563...	156...
Interface	0	0 X1			EUCHNER-MBM	
Port 1	0	0 X1 P1			Port 1	
Port 2	0	0 X1 P2			Port 2	
PROFIsafe 2 Bytes_1	0	1	2...7	2...7	PROFIsafe 2 Bytes	
MBM DIAGNOSE EXTENDED_1	0	2	8...9	8	MBM DIAGNOSE EXTENDED	
2 MGB2-L1-MLI-U-Y0000-BJ-136776 Dia...	0	3	10...12	9	MGB2-L1-MLI-U-Y0000-BJ...	136...
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	3 1	10...12	9	MGB2-L1-MLI-U-Y0000-BJ...	
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	3 2				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	3 3				
3 MGB2-L1-MLI-U-Y0000-BJ-136776 Dia...	0	4			MGB2-L1-MLI-U-Y0000-BJ...	136...
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	4 1	13...15	10	MGB2-L1-MLI-U-Y0000-BJ...	
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	4 2				
4 MSM-1-P-CA-PPP-SVHD-9000003	0	4 3	16	11	MSM-1-P-CA-PPP-SVHD-9...	SWF...
5 MGB2-L1-MLI-U-Y0000-BJ-136776 Dia...	0	5			MGB2-L1-MLI-U-Y0000-BJ...	136...
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	5 1	17...19	12	MGB2-L1-MLI-U-Y0000-BJ...	
6 MSM-1-P-CA-PPP-A9-127040	0	5 2	20	13	MSM-1-P-CA-PPP-A9-127...	127...
7 MSM-1-P-CA-BPP-A1-136687 Diagn...	0	5 3	21...22	14	MSM-1-P-CA-BPP-A1-136...	136...
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	6				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	7				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	8				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	9				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	10				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	11				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	12				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	13				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	14				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	15				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	16				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	17				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	18				
MGB2-L1-MLI-U-Y0000-BJ-136776 ...	0	19				

Fig. 6: Example system layout

11.9.2. List of the parameters that can be set per module/submodule

Module/submodule	PROFINET, PROFIsafe	Parameter	Setting range / [default value]	Description
Bus module MBM	PROFINET	Device name	Arbitrary designation	The device name can be assigned as required. Important: It must match the name in the configuration software. Tip: On replacing a faulty device, it is recommended to delete the name in the device (factory setting). If there is no name in the device, the existing name in the system for the previous device is entered automatically on starting. Prerequisite: Your PROFINET topology must be correctly configured.
		IP address		If a dynamic IP address is not assigned by your control system, a static IP address can be entered here.
		Update time	250 µs ... 512 ms [automatic]	Interval at which the inputs/outputs are updated.
	PROFIsafe	F_Dest_Add	1 ... 65534	Address of the PROFIsafe device.
		F_Source_Add	1 ... 65534	Address of the control system connected to the device.
		F_WD_Time	150 ... 65535 ms [600]	Time within which the device must react to a control system request. Error if time exceeded.
Locking module MGB2	PROFIsafe	Solenoid control from the safety program Important: Setting has an effect on the safety function (see the operating instructions of your locking module for details)	Yes/No [Yes]	Parameter can be changed only for MGB2-L2 devices.
	PROFINET	Solenoid control from the standard program Important: Setting has an effect on the safety function (see the operating instructions of your locking module for details)	Yes/No [No]	For MGB2-L1: Here you can set whether the guard locking solenoid is additionally to be controlled using a non-safe bit. For MGB2-L2: Here you can set whether a) The guard locking solenoid is additionally to be controlled using a non-safe bit. For this purpose, "Yes" is set. b) The guard locking solenoid is to be controlled using only a non-safe bit. For this purpose, "Yes" is set. The "Solenoid control from the safety program" parameter must be set to "No" for this purpose. c) Guard locking is not to be used at all. For this purpose, "No" is set. The "Solenoid control from the safety program" parameter must also be set to "No" for this purpose.
		Escape release alarm	Yes/No [No]	Here you can set whether the actuation of the escape release is to cause an error message.
Submodules	PROFINET	Submodule alignment	Do not check/top/bottom [Do not check]	For submodules on which installation rotated by 180° cannot result in incorrect operation or functional problems, the alignment check can be disabled here. With "top" or "bottom", it is checked whether the position marking for S1 is at the "top" or "bottom" of the submodule (for marking, see data sheet for the submodule).
Submodules with illuminated control elements or submodules with indicators or stacklight for expansion module MCM	PROFINET	Flashing frequency H1	1 ... 255 (corresponds to 0.1 ... 25.5 Hz)	Here you can set the frequency at which the indicator is to flash. Prerequisite: the corresponding output bit for the flashing function must be set.
		Flashing frequency H2	1 ... 255 (corresponds to 0.1 ... 25.5 Hz)	
		Flashing frequency H3	1 ... 255 (corresponds to 0.1 ... 25.5 Hz)	
		Flashing frequency H4 (only for stacklight)	1 ... 255 (corresponds to 0.1 ... 25.5 Hz)	

11.10. Line swap

During the first starting process, the current MLI topology will be saved if the control system configuration matches the MLI topology.

When the system is restarted, the bus module detects if the position of an MLI device has changed or the device is being operated on a different MLI line.

The bus module additionally reports an error if devices were removed or added.

This is intended to prevent devices that were incorrectly connected after servicing from entering safe mode, for example.

If the system reports a line swap error, the MLI topology must be checked and corrected if necessary. Once the MLI topology matches the stored topology again, the system enters normal operation again after the restart.

Replacement devices are not recognized as errors if there are no major changes in the safe data of the MLI devices. In this case, the user is responsible for testing the safe function.

An intentional change of the MLI topology must be reset via factory reset using the DIP switches (see chapter 13.3. *Resetting system to factory settings (factory reset) on page 44*). The MLI topology will be saved the next time the system is started.

11.11. Replacing submodules



CAUTION

Risk of damage to equipment or malfunction as a result of uncontrolled machine stop.

- The communication within the system is interrupted by the replacement of a submodule, and the safe bits are reset. If a process is running, this situation can result in an uncontrolled stop and damage to the installation or the product. Before replacement, make sure the installation is in a suitable operating status.



NOTICE

Pay attention to the information on the replacement of a submodule in the operating instructions for the related module. On submodules with a safety function, the correct function must be tested after replacement before the system enters normal operation again.

The replacement of submodules MSM while in operation is also possible (pay attention to safety note above). As soon as the system detects a correct submodule, the submodule is ready for operation. The system reacts as follows on a replacement:

1. If the submodule MSM is removed, the SLOT LED illuminates red, interrupted by 1x green flash. In addition, the SF LED on the bus module MBM illuminates red.
2. If the submodule MSM contains a safety function, the related bit on the bus is cleared as soon as the submodule has been removed.
3. If an identical submodule is inserted with the same alignment, the fault display goes out and the bit is transmitted on the bus again to suit the actual situation.

11.12. Replacing modules



CAUTION

Risk of damage to equipment or malfunction as a result of uncontrolled machine stop.

- The communication within the system is interrupted by the replacement of a module, and the safe bits are reset. If a process is running, this situation can result in an uncontrolled stop and damage to the installation or the product. Before replacement, make sure the installation is in a suitable operating status.

Modules (e.g. locking module or expansion module) can be replaced only in combination with a restart of the overall system. On the disconnection of the module connection, the system enters into a fault state. The related module and all downstream modules remain inactive until the overall system is restarted (fault state).

11.13. Changing the configuration

Changes to the configuration of the overall system must always be made in the configuration software for your control system (see chapter 11.7. *Integrating into PROFINET and PROFIsafe on page 30*). Depending on the change, a factory reset might also be necessary.

12. Overview of data blocks for modules and submodules



Important!

- ▶ You will find the exact data structure for your device on the supplementary data sheet.
- ▶ With some modules and submodules, you have the choice between a **standard configuration (basic)** that has basic status, signaling and control functions or an **extended configuration** that also contains an additional byte with exact error codes for diagnostic purposes.
- ▶ The output data (OUT) evaluated internally in the bus module MBM are set to 0x00 (cleared) on:
 1. Power on (application of the power supply)
 2. PROFINET connection interruption (e.g. disconnection of terminal plug)
 3. PLC STOP (IOPS=BAD)

12.1. Data blocks for bus module MBM

12.1.1. Safe bits

Bus modules do not have any dedicated safe bits.

12.1.2. Non-safe bits

Standard configuration (basic)	Extended configuration with additional diagnostics byte
BM_ E_G - BM_ E_SYS - - BM_ E_ML2 BM_ E_ML1 BM_ D_RUN BM_ ACK_G	BM_ E_G - BM_ E_SYS - - BM_ E_ML2 BM_ E_ML1 BM_ D_RUN Diagnosebyte mit Fehlercodes optional steckbar Diagnostic byte with error codes (optional pluggable) BM_ ACK_G

Input/output	Bit identifier	Meaning	Condition for setting	Condition for resetting
Input	BM_D_RUN	Diagnostics run mode	Device in operation	Device is not supplying any data
	BM_E_ML1	Error status bit Line 1	Fault on a module OR submodule OR EMC problem OR max. cable length exceeded	Automatic if error rectified OR acknowledgment bit BM_ACK_G is set for 500 ms (min. 350 ms and max. 750 ms)
	BM_E_ML2	Error status bit Line 2	Fault on a module OR submodule OR EMC problem OR max. cable length exceeded	Automatic if error rectified OR acknowledgment bit BM_ACK_G is set for 500 ms (min. 350 ms and max. 750 ms)
	BM_E_SYS	Error status bit Overall system	Any error in the overall system	Automatic if error rectified OR acknowledgment bit BM_ACK_G is set for 500 ms (min. 350 ms and max. 750 ms)
	BM_E_G	Error status bit General module error	Error in the module	Automatic if error rectified OR acknowledgment bit BM_ACK_G is set for 500 ms (min. 350 ms and max. 750 ms)
Output	BM_ACK_G	Acknowledgment bit for general errors	Control via PLC Resets error bit BM_E_G. Acknowledgment bit must be set for 500 ms (min. 350 ms and max. 750 ms).	

12.2. Data blocks for interlocking/locking module MGB2-I / MGB2-L

12.2.1. Safe bits

Input/output	Bit identifier	Meaning	Condition for setting	Condition for resetting
Input	LM_FI_SK	Safe input Door position	Door closed and bolt tongue inserted into interlocking/locking module	Door open OR error in transponder
	LM_FI_UK	Safe input Guard lock monitoring (only for MGB2-L)	Door closed AND locked	Guard locking open OR error in guard locking
Output	LM_FO_CL	Safe control of guard locking (only for MGB2-L)	Control via PLC Set = guard locking released Not set = guard locking active	

12.2.2. Non-safe bits

Standard configuration (basic)								IN
LM_E_G	LM_E_ER	LM_E_SM2	LM_E_SM1	-	LM_I_UK	LM_I_SK	LM_D_RUN	
-	-	-	-	-	LM_I_OL	LM_I_OT	LM_I_OD	
LM_ACK_G	LM_ACK_ER	-	-	-	-	-	LM_O_CL	
Extended configuration with additional diagnostics byte								IN
LM_E_G	LM_E_ER	LM_E_SM2	LM_E_SM1	-	LM_I_UK	LM_I_SK	LM_D_RUN	
-	-	-	-	-	LM_I_OL	LM_I_OT	LM_I_OD	
Diagnosebyte mit Fehlercodes optional steckbar Diagnostic byte with error codes (optional pluggable)								
LM_ACK_G	LM_ACK_ER	-	-	-	-	-	LM_O_CL	OUT

Input/output	Bit identifier	Meaning	Condition for setting	Condition for resetting
Input	LM_D_RUN	Diagnostics run mode	Device in operation	Device is not supplying any data
	LM_I_SK	Non-safe input Door and bolt position	Door closed and bolt tongue inserted into interlocking/locking module	Door open OR error in transponder
	LM_I_UK	Non-safe input Guard lock monitoring	Door closed AND locked	Guard locking open OR error in guard locking
	LM_E_SM1	Error status bit for submodule 1	Error in submodule	Automatic if error rectified
	LM_E_SM2	Error status bit for submodule 2	Error in submodule	Automatic if error rectified
	LM_E_ER	Error status bit for escape release	Actuation of the escape release. This behavior must be set in the parameters.	Acknowledgment bit LM_ACK_ER is set for min. 50 ms
	LM_E_G	Error status bit General module error	Error in module OR a submodule installed	Automatic if error rectified OR acknowledgment bit LM_ACK_G is set for min. 50 ms
	LM_I_OD	Non-safe input Door position	Door closed	Door open
	LM_I_OT	Non-safe input Bolt tongue	Bolt tongue inserted into interlocking/locking module	Bolt tongue not inserted into interlocking/locking module
	LM_I_OL	Non-safe input Guard locking	Guard locking active	Guard locking released
Output	LM_O_CL	Non-safe control of guard locking	Can be used as additional, non-safe control bit for guard locking. This behavior must be set in the parameters. Control via PLC Bits LM_FO_CL AND LM_O_CL set = guard locking released Bit LM_FO_CL OR LM_O_CL not set = guard locking active	
	LM_ACK_ER	Acknowledgment bit for escape release error	Control via PLC Resets error bit LM_E_ER. Acknowledgment bit must be set for 500 ms (min. 350 ms and max. 750 ms).	
	LM_ACK_G	Acknowledgment bit for general errors	Control via PLC Resets error bit LM_E_G. Acknowledgment bit must be set for 500 ms (min. 350 ms and max. 750 ms).	

12.3. Data blocks for expansion module MCM

Expansion modules can contain up to four submodules and evaluate them. They do not have any further dedicated function.

12.3.1. Safe bits

Expansion modules do not have any dedicated safe bits.

12.3.2. Non-safe bits

Standard configuration (basic)										Extended configuration with additional diagnostics byte											
EM_ E_G EM_ E_SM4 EM_ E_SM3 EM_ E_SM2 EM_ E_SM1 - - EM_ D_RUN										IN	EM_ E_G EM_ E_SM4 EM_ E_SM3 EM_ E_SM2 EM_ E_SM1 - - EM_ D_RUN										IN
EM_ ACK_G - - - - - - -										OUT	Diagnosebyte mit Fehlercodes optional steckbar Diagnostic byte with error codes (optional pluggable)										IN
EM_ ACK_G - - - - - - -										OUT	EM_ ACK_G - - - - - - -										OUT

Standard configuration with stacklight (basic)											Extended configuration with stacklight and additional diagnostics byte										
EM_ EM_ EM_ EM_ EM_ - - EM_ E_G E_SM4 E_SM3 E_SM2 E_SM1																					

Input/output	Bit identifier	Meaning	Condition for setting	Condition for resetting
Input	EM_D_RUN	Diagnostics run mode	Device in operation	Device is not supplying any data
	EM_E_SM1	Error status bit for submodule 1	Error in submodule	Automatic if error rectified
	EM_E_SM2	Error status bit for submodule 2	Error in submodule	Automatic if error rectified
	EM_E_SM3	Error status bit for submodule 3	Error in submodule	Automatic if error rectified
	EM_E_SM4	Error status bit for submodule 4	Error in submodule	Automatic if error rectified
	EM_E_G	Error status bit General module error	Error in module OR a submodule installed	Automatic if error rectified OR acknowledgment bit BM.ACK_G is set for 500 ms (min. 350 ms and max. 750 ms)
Output	EM_ACK_G	Acknowledgment bit for general errors	Control via PLC Resets error bit EM_E_G. Acknowledgment bit must be set for 500 ms (min. 350 ms and max. 750 ms).	
	EM_O_H1	Lamp H1	Only for configurations with stacklight. Control bit for lamp H1...H4. Control via PLC (HIGH = illuminated).	
	EM_O_H2	Lamp H2		
	EM_O_H3	Lamp H3		
	EM_O_H4	Lamp H4		
	EM_O_H1_B	Lamp H1 flashing function	Only for configurations with stacklight. Control bit for lamp H1...H4 flashing function. Control via PLC must be used in combination with the corresponding control bit for the lamp (EM_O_H.). Switching logic based on the example of H1: EM_O_H1 AND EM_O_H1_B = H1 flashes To set the flashing frequency, see chapter 11.9.2. List of the parameters that can be set per module/submodule on page 37.	
	EM_O_H2_B	Lamp H2 flashing function		
	EM_O_H3_B	Lamp H3 flashing function		
	EM_O_H4_B	Lamp H4 flashing function		

12.4. Data blocks for submodules

For the data blocks your submodule contains, refer to the associated data sheet. See also chapter 11.3. *Information on the related data sheets.*

12.5. Replacing a bus module MBM without programming device

If servicing is required, the bus module MBM is easy to replace with a new module. For this purpose, the following prerequisites must be met:

- The DIP switch settings (PROFIsafe address) on the new device must match those on the old device. With DIP switches 000000000001 (PROFIsafe address type 2), the F_Dest_Add and the F_Source_Add must be assigned via the web server.
- Your PROFINET master must support the automatic replacement of PROFINET devices.
- Your PROFINET topology must be correctly configured.
- The replacement device must be connected to the same port as its predecessor.
- There must be no device name in the bus module.
This field is empty in the delivery state. MBMs that already contain a name must first be reset to the factory settings.

Once these conditions are met, simply replace the old MBM with the new MBM.

12.6. Handle module teach-in operation (only for systems with locking module MGB2 uni-code)

The handle module must be assigned to the locking module using a teach-in function before the system comprising locking module and handle module forms a functional unit.

You will find a detailed description of the teach-in operation in the operating instructions for your locking/interlocking module.

13. Diagnostics, troubleshooting and aids

All error codes are listed in the following. If you use the data blocks with **extended configuration** in the configuration software for your control system, the error code is output in the corresponding byte. In the **standard configuration**, only a corresponding error status bit is set and the system indicates the error via the diagnostics LEDs.



Important!

The error code given in the tables below is sequential and starts with 0x01. You must add any upstream error codes from PROFINET or the control system to the error codes stated. For PROFINET, the offset to be taken into account is 0x100.

Most messages are also displayed on the devices.

Key to symbols			LED not illuminated
			LED illuminated
			LED flashes three times
			LED flashes at 1 Hz
			LED flashes with a long turn-on time
			Any state

13.1. Reset and restart

To acknowledge general errors and restart the system, disconnect the bus module MBM from the power supply for a few seconds.

13.2. Acknowledging errors

To acknowledge errors, set the respective acknowledgment bit for 500 ms (min. 350 ms and max. 750 ms). You will find an overview of the error messages and reset conditions from chapter 13.5. *General errors*.

13.3. Resetting system to factory settings (factory reset)

You can reset the device using one of the following methods:

- With the aid of the configuration software for your control system (this resets only the PROFINET portion).
Example for Siemens TIA-Portal: in the "Online & Diagnostics" dialog box.
- With the aid of the DIP switches in the bus module MBM (this resets the overall system including the MLI topology).
Procedure: Switch off system, set "RST" DIP switch to "ON" position and restart system. If DIA and MAINT flash alternately, switch the system off, set the "RST" DIP switch to "OFF" position and restart the system.
See also chapter 9.1. *DIP switches on page 17*.
- Check the safe function of the safeguard and, if necessary, other safety functions after every factory reset.

13.4. Diagnostics with the aid of the device web interface

The device has an internal device web interface. The device web interface can be used at any time in operation if the function is activated. Settings can be made on the device.

The following diagnostics information is provided:

- › Overview of all modules and submodules installed
- › Status and version of all modules and submodules installed
- › IP address and device name of the bus module MBM
- › PROFIsafe address and PROFIsafe address type
- › Error list for each module and submodule
- › Error list for the overall system

The error numbers indicated correspond to those in the error tables below from chapter 13.5 on page 47.

13.4.1. Using device web interface

Proceed as follows:

1. Set “WWW” DIP switch to “on” position. See also chapter 9.1 on page 17.
Notice: The change is effective only after a restart.
 2. Connect device to a PC or other suitable input/output device using a network cable.
 3. Open the device web interface in the browser (IP address: XXX.XXX.XXX.XXX).
- ➔ The HOME page appears.

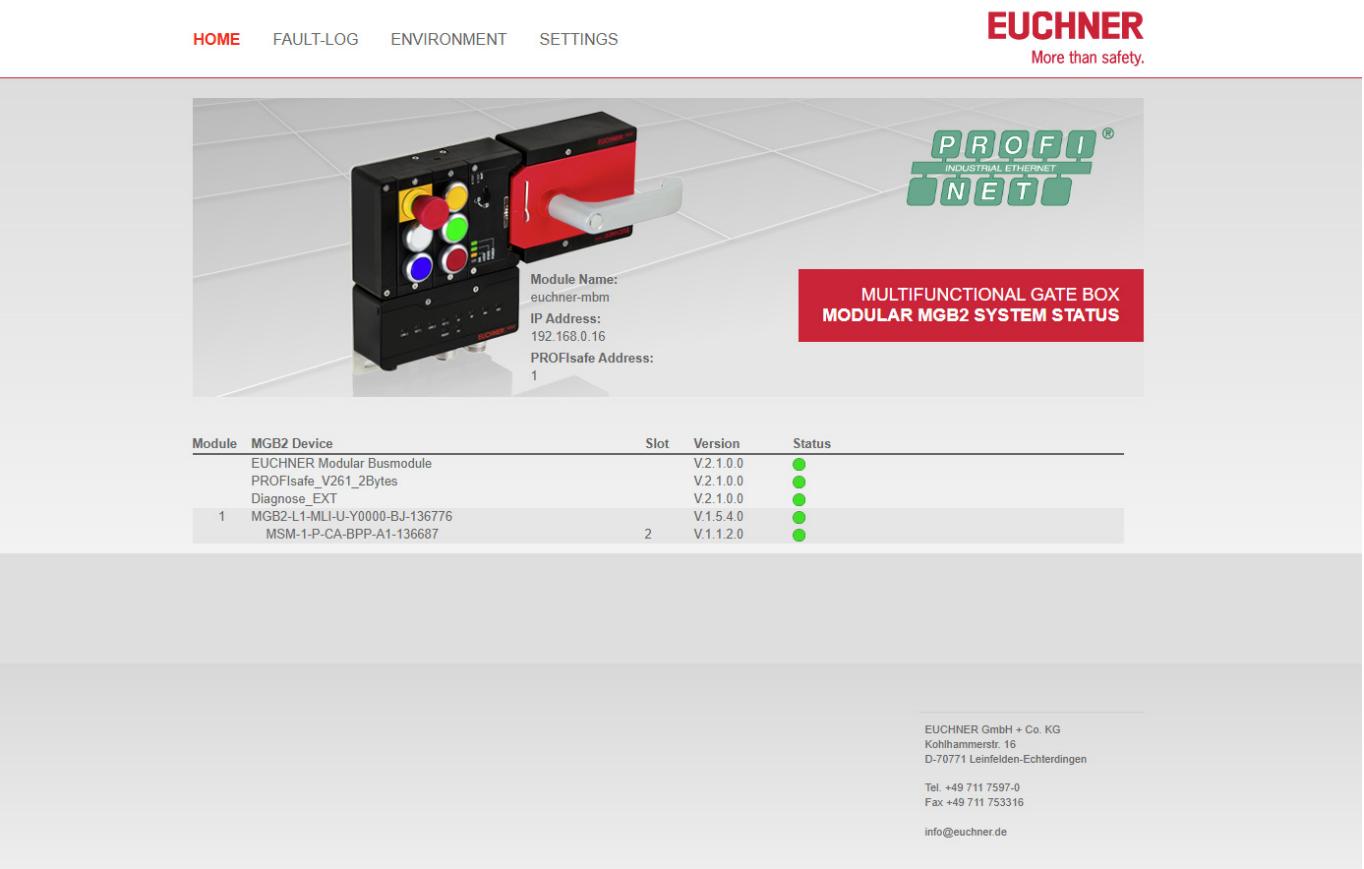


Fig. 7: HOME page on the device web interface in the bus module MBM

There you can see information on the bus module MBM and on the modules and submodules connected. Devices with errors have a red status.

On the HOME page, you can do the following:

- › Click the name of a module to open the diagnostics page for the module.
- › Click FAULT-LOG to display a fault log for the overall system. All current and previous errors since setup are listed there. The error list can also be downloaded from the device. With this file, our support team will be able to provide specific assistance if you have problems. The download link is at the end of the error list.
Click ENVIRONMENT to display available environment parameters.
- › Click SETTINGS to download the HTTPS certificate. The administrator area is also here. This can be protected by a user-assigned password.

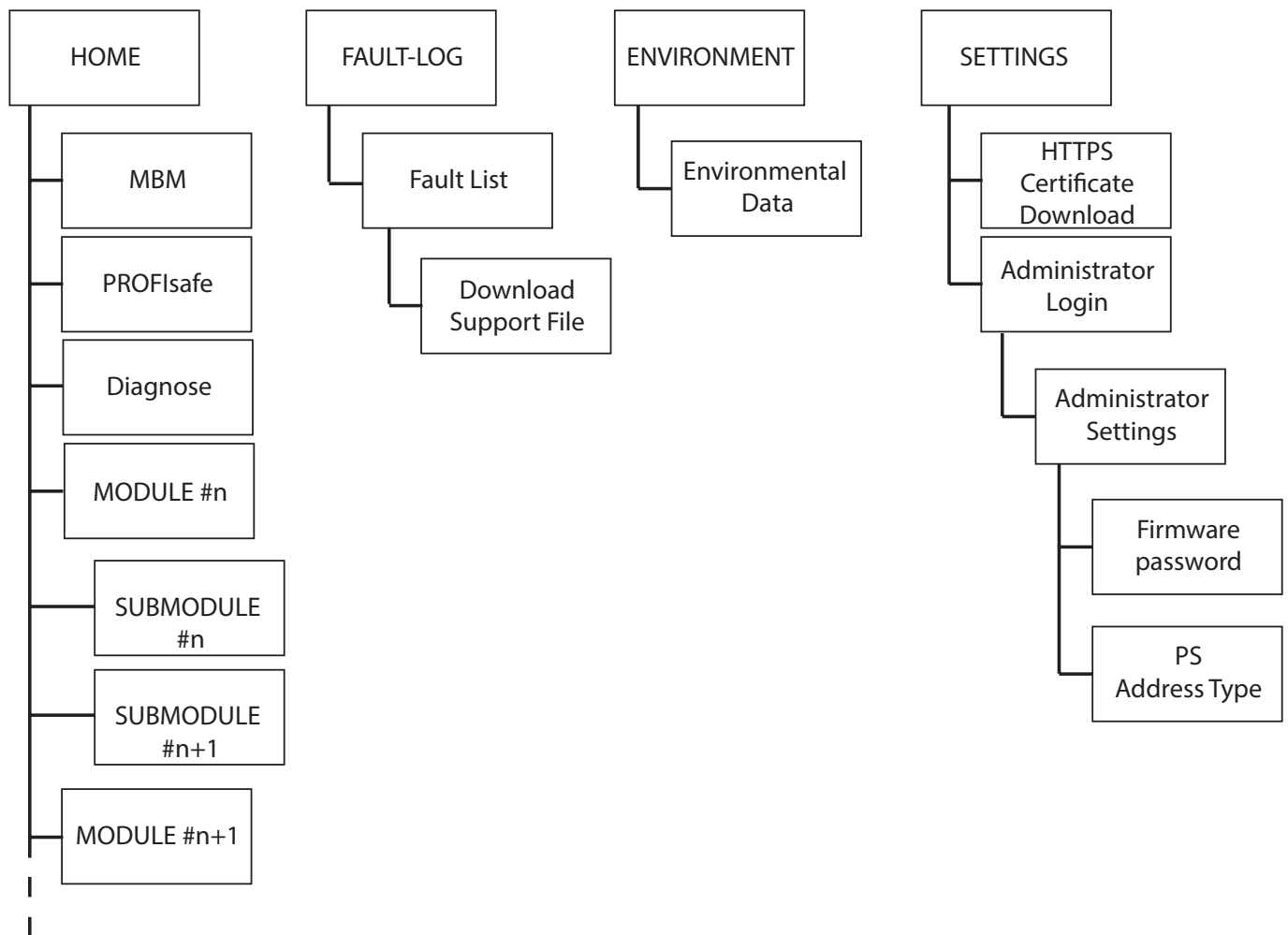


Fig. 8: Site map for the device web interface in the bus module MBM

13.4.2. Using password



Important!

- › EUCHNER recommends assigning an individual password for each device.
- › If a default password is used for different devices instead of individual passwords, it is essential to observe the following points:
 - The use of default passwords might facilitate unauthorized access to the network and the devices.
 - If a network error occurs during the firmware update process, devices not intended for a firmware update might be updated.

13.5. General errors

MBM

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays							
							Bus module							
							LINK 1 / LINK 2	ACT 1 / ACT 2	SF	BF	DIA	US1	MAINT	PS
0x01 ... 0x06	Internal fault	Internal device fault. Device is no longer functional.	Internal fault	Latching	Restart system. If the error persists, contact our support team.	BM_E_G	○	○	○	○			○	○

Interlocking/locking module

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays					
							Interlocking/locking module					
							POWER	STATE	LOCK	DIA	SLOT 1	SLOT 2
0x01 ... 0x06	Internal fault	Internal device fault. Device is no longer functional.	Internal fault	Latching	Restart system. If the error persists, contact our support team.	LM_E_G	✱	○	○	✱	○	○

MCM

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays				
							Interlocking/locking module				
							POWER/FC	STATE	DIA	SLOT RED	SLOT GREEN
0x01 ... 0x06	Internal fault	Internal device fault. Device is no longer functional.	Internal fault	Latching	Restart system. If the error persists, contact our support team.	EM_E_SM	✱	○	✱	○	○

13.6. Teach-in errors and configuration errors

MBM

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays							
							Bus module							
							LINK 1 / LINK 2	ACT 1 / ACT 2	SF	BF	D/A	US1	MAINT	PS
OxAE	Configuration error	Configuration in the control system does not match the actual configuration. Modules might be swapped or in the wrong location.	Config-uration error	Latching	Restore the correct configuration and restart the system. A factory reset may be necessary.	BM_E_G				○				
OxEA	Topology error	Saved topology does not match the actual topology. Modules might be swapped or in the wrong location.	Topology error	Latching	Restore the correct topology and restart the system. An intentional change of the MLI topology must be reset via factory reset.	BM_E_G								
OxEB	Topology error	Saved topology does not match the actual topology. Modules might have been added or removed.	Topology error	Latching	Restore the correct topology and restart the system. An intentional change of the MLI topology must be reset via factory reset.									

Interlocking/locking module

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays					
							Interlocking/locking module					
							POWER	STATE	LOCK	DIA	SLOT 1	SLOT 2
Ox1F	Actuator/handle module could not be taught-in	Actuator/handle module not detected often enough during teach-in operation or removed during teach-in operation.	Teach-in error	Latching	Restart teach-in operation. Make sure the handle module is not removed during the teach-in operation. (Door closed, bolt tongue inserted.)	LM_E_G			○		○	○
Ox22	Solenoid configuration error	Single-channel solenoid control	Configuration error	Latching	Set solenoid monitoring in the settings							

13.7. Transponder errors

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays					
							Interlocking/locking module					
							POWER	STATE	LOCK	DIA	SLOT 1	SLOT 2
0x42	Invalid handle module detected	Handle module is not valid or handle module is faulty.	Transponder error	Latching	Restart teach-in operation. If the error persists, contact our support team.	LM_E_G						
0x25	Disabled actuator detected	Already taught-in but disabled actuator has been detected.	Transponder error	Latching	Restart teach-in operation with a new handle module or use taught-in handle module if a teach-in operation was not intended.	LM_E_G						

13.8. Environment errors

MBM

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays							
							Bus module							
							LINK 1 / LINK 2	ACT 1 / ACT 2	SF	BF	DIA	US1	MAINT	PS
0x60	Supply voltage too high	Overvoltage	Environment error	Resettable/latching	Decrease supply voltage. Pay attention to technical data.	BM_E_G								
0x61	Supply voltage too low	Low voltage	Environment error	Resettable	Increase supply voltage or check system topology. Pay attention to technical data and max. number of modules/submodules. Possibly excessively long cables.									

Interlocking/locking module

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays					
							Interlocking/locking module					
							POWER	STATE	LOCK	DIA	SLOT 1	SLOT 2
0x60	Supply voltage too high	Overvoltage	Environment error	Resettable	Decrease supply voltage. Pay attention to technical data.	LM_E_G			O			
0x61	Supply voltage too low	Low voltage	Environment error	Resettable	Increase supply voltage or check system topology. Pay attention to technical data and max. number of modules/submodules. Possibly excessively long cables.							
0x62	Temperature too high	Temperature in the housing too high	Environment error	Latching	Check whether the system is operating in the temperature range specified. Pay attention to technical data.							
0x63	Temperature too low	Temperature in the housing too low	Environment error	Latching	Check whether the system is operating in the temperature range specified. Pay attention to technical data.							

MCM

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays				
							Interlocking/locking module				
							POWER/FC	STATE	DIA	SLOT RED	SLOT GREEN
0x60	Supply voltage too high	Overvoltage	Environment errors	Resettable	Decrease supply voltage. Pay attention to technical data.	EM_E_SM					
0x61	Supply voltage too low	Low voltage	Environment error	Resettable	Increase supply voltage or check system topology. Pay attention to technical data and max. number of modules/submodules. Possibly excessively long cables.						
0x62	Temperature too high	Temperature in the housing too high	Environment errors	Latching	Check whether the system is operating in the temperature range specified. Pay attention to technical data.						
0x63	Temperature too low	Temperature in the housing too low	Environment error	Latching	Check whether the system is operating in the temperature range specified. Pay attention to technical data.						

13.9. Communication errors

MBM

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays									
							Bus module									
							LINK 1 / LINK 2	ACT 1 / ACT 2	SF	BF	DIA	US1	MAINT	PS		
0x74	MLI1 disrupted	Communication disrupted	Communi- cation error	Latching	Check cables and plug connectors for correct seating and damage. Restart system.	BM_E_G										
0x75	MLI2 disrupted	Communication disrupted	Communi- cation error	Latching	Check cables and plug connectors for correct seating and damage. Restart system.											
0x78	Safety communication with device lost	Communication disrupted	Communi- cation error	Resetta- ble	Check cables and plug connectors for correct seating and damage.							4x rd				
0x79	Non-safety communication with device lost	Communication disrupted	Communi- cation error	Resetta- ble	Check cables and plug connectors for correct seating and damage.											
0x7A	Maximum number of modules/submodules exceeded		Communi- cation error	Latching	Reduce the number of modules/submodules in your system. Max. 18 devices.											
0x7B	Bus open circuit error	No Link signal; Ethernet cable is not connected	Communi- cation error	Resetta- ble	Check PROFINET connection.	BM_E_G					1 Hz					1x

Interlocking/locking module

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays					
							Interlocking/locking module					
							POWER	STATE	LOCK	DIA	SLOT 1	SLOT 2
0x74	MLI1 disrupted	Communication disrupted	Communication error	Latching	Check cables and plug connectors for correct seating and damage. Restart system.	LM_E_G						

MCM

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays				
							Interlocking/locking module				
							POWER/FC	STATE	DIA	SLOT RED	SLOT GREEN
0x74	MLI1 disrupted	Communication disrupted	Communication error	Latching	Check cables and plug connectors for correct seating and damage. Restart system.	EM_E_SM	 1x	○			

13.10. Plausibility errors

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays			
							Interlocking/locking module			
							POWER	STATE	DIA	LOCK
0x88	Plausibility error: bolt fracture	Transponder for the bolt has been detected without the door closed.	Plausibility error	Resettable	Check function of the handle module. Pay attention to damage. Replace handle module if necessary. Acknowledge error with LM_ACK_G.	LM_E_G		○		 1x
0x8A	Plausibility error: signal sequence	Transponder has been detected or removed without the bolt handle having been moved. Door may have been slammed too fast.	Plausibility error	Resettable	Open door, acknowledge error with LM_ACK_G. Close door more slowly. On repeated occurrence, contact our support team.					
	Escape release	Message that the escape release has been actuated (only if set in the parameters).	Plausibility error	Resettable	Rectify error via general acknowledgment bit LM_ACK_G or via acknowledgment bit LM_ACK_ER for escape release error.	LM_E_G/ LM_E_ER				

13.11. Submodule errors

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting/ acknowledgment	LED displays	
						Submodule	
						SLOT RED	SLOT GREEN
	Incorrect submodule	Submodule type detected does not correspond to the submodule type saved	Incorrect submodule	Submodule will be ignored; no effect on overall system	Replace submodule, modify system topology or restart system		 3x
	Submodule missing	Submodule missing, even though a submodule has been taught-in for the slot	Submodule missing	Missing submodule will be ignored; no effect on overall system	Install submodule or modify system topology		 1x
	Submodule rotated by 180°	Submodule is installed rotated by 180°	Submodule rotated by 180°	Submodule will be ignored; no effect on overall system	Rotate submodule by 180°		 2x
	Internal submodule fault	Internal device fault. Submodule is no longer functional.	Internal submodule fault	Submodule will be ignored; no effect on overall system	Replace submodule		○
0xA0	Error in the safety equipment (can be reset automatically)	E.g.: discrepancy error (emergency stop, enabling switch, key-operated rotary switch, acknowledgment pushbutton)	Safety error in submodule	Latching	For submodules to which an external device is connected (e.g. enabling switch): check correct function of the external device. For errors in the submodule: replace faulty submodule and send to the manufacturer.	 1 Hz	○

13.12. PROFINET errors

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays							
							Bus module							
							LINK 1 / LINK 2	ACT 1 / ACT 2	SF	BF	DIA	US1	MAINT	PS
0x10C	Parameter setting error	The assembly has detected a parameter setting error. Parameter setting errors can be: - The assembly cannot evaluate any parameters (examples of possible causes: unknown parameters, invalid parameter combination). - No parameters have been assigned yet to the assembly.	Application error	Latching	Check parameters and correct these. Then load the parameters into the assembly again.								 2x rd	

13.13. PROFIsafe errors

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays							
							Bus module							
							LINK 1 / LINK 2	ACT 1 / ACT 2	SF	BF	DIA	US1	MAINT	PS
0x0150	F_DEST_ADDR	Erroneous safety destination address	Parameter setting error	Latching	The PROFIsafe address set on the device does not match the address set in the configuration tool for your control system. Either modify the DIP switch setting or change the information in the parameter Parameter F_Dest_Add.	BM_E_G								 1x
0x0151	F_DEST_ADDR	Safety destination address invalid	Parameter setting error	Latching	The PROFIsafe address set in the configuration tool for your control system has an impermissible value. Check the parameter setting.									
0x0152	F_SOURCE_ADDR	Safety source address invalid	Parameter setting error	Latching	The PROFIsafe source address set in the configuration tool for your control system has an impermissible value. Check the parameter setting.									
0x0153	F_WD_TIME	Watchdog timer value is 0 ms	Parameter setting error	Resettable	The value for the watchdog timer set in the configuration tool for your control system has an impermissible value. Check the parameter setting.									
0x0154	F_SIL	Parameter F_SIL exceeds SIL for the specific device application	Parameter setting error	Resettable	The value for F_SIL set in the configuration tool for your control system has an incorrect value. Check the parameter setting.									
0x0155	F_CRC_Length	Parameter F_CRC_LENGTH does not correspond to the values generated			The value for the length of the CRC set in the configuration tool for your control system has an incorrect value. Check the parameter setting.									
0x0156	F_Version	Version for F parameter set incorrectly	Parameter setting error	Resettable	An incorrect version or an invalid F_Version has been detected. Check the parameter setting.									
0x0157	F_CRC1	CRC1 error	Parameter setting error	Resettable	The CRC value calculated does not match the value in the GSDML file. There may be an incorrect value in the GSDML file or incorrect transmission due to interference (e.g. EMC problems).									
0x0158	Device specific diagnosis information	Device-specific error			Information that a device-specific error has occurred. See error codes from chapter 13.5. General errors on page 47ff									
0x0159		Watchdog Time iParameter saving exceeded												

Error code	Error designation	Meaning	Error category	Error behavior	Troubleshooting	Corresponding error/status bit	LED displays							
							Bus module							
							LINK 1 / LINK 2	ACT 1 / ACT 2	SF	BF	DIA	US1	MAINT	PS
0x0162		F_Block_ID not supported	Parameter setting error	Resettable	Check the parameters and correct them. Then load the parameters into the assembly again.	BM_E_G								
0x0163	CRC2 error		Communication error	Resettable	Read the CRC2 error memory. Restart communication.				○	○			○	
0x0164	F_WD_Time or F_WD_Timer_2 elapsed	Transfer error: timeout	Communication error	Resettable	Restart communication.									1x

14. Updating firmware

The device's firmware can be updated using the EUCHNER Device Update tool. You will find further information in the software manual.



WARNING

Loss of the safety function

A firmware update can change or expand functions.

Observe the following points to ensure the safety function:

- › Carefully observe the release notes for the respective firmware version prior to the update process. Ensure that the changes the firmware update triggers in the device continue to comply with the requirements of the overall system.
 - Perform a risk assessment on the overall system before the update if necessary, because the update could change functions or processes in the EUCHNER device.
 - Observe and follow the instructions in the software manual when updating the firmware.

14.1. Running EUCHNER Device Update



NOTICE

Damage to the device

The device can be damaged when the firmware is updated.

- › Make sure to use only one instance of the EUCHNER Device Update tool. Sending several broadcasts simultaneously from different instances to search for devices can damage the device.
- › Ensure that a possible network connection loss does not result in losing data and damaging the device. While the network is being scanned, an overload might occur.
- › Ensure a stable power supply for the device.
- › Ensure that the automatic restart of the device after a successful update is not interrupted.



Important!

- › After the update, check the update report to determine whether and on which devices the update process was successful.
- › Ensure that the firmware update is recorded in the machine documentation using the automatically generated update report.
- › Ensure that the device documentation corresponding to the update is available and is observed after the device update.

15. Technical data



NOTICE

If a data sheet is included with the product, the information on the data sheet applies.

Parameter	Value
Housing material	Fiber glass reinforced plastic Die-cast zinc, nickel-plated, stainless steel
Dimensions	See dimension drawing
Weight, bus module	0.8 kg
Ambient temperature	-25 ... +55 °C at UB = 24 V
Degree of protection	IP65
Safety class	III
Degree of contamination	3
Installation position	Any
Connection options, power supply ¹⁾	2 x push-pull power or 2 x plug connectors 7/8" acc. to ANSI/B93.55M-1981 or 2 x M12 plugs (L-coded), 5-pin, acc. to IEC 61076-2-101 or 2 x M12 plugs (L-coded), 4-pin, acc. to IEC 61076-2-101
Connection, bus ¹⁾	2 x RJ 45, push-pull, acc. to IEC 61076-3-117 variant 14, screened or 2 x M12 (D-coded) according to IEC 61076-2-101
Connecting cable, bus	PROFINET I/O cable, at least cat. 5e
Operating voltage U _B	DC 24 V +20%/-15% (PELV – see chapter 10. Electrical connection)
Current consumption, max. (only bus module)	200 mA
Current consumption, max. (bus module and all connected modules/submodules)	
- Push-pull plug connector/plug connector 7/8" acc. to ANSI/B93.55M-1981	4 A
- Plug connector M12 (L-coded) ²⁾	3.2 A
Maximum feed-in current in the connection block	
- Push-pull plug connector	16 A
- Plug connector M12 (L-coded) ²⁾	12 A
- Plug connector 7/8" acc. to ANSI/B93.55M-1981	6 A
Fuse protection for power supply, external	Min. 4 A slow-blow
Safety outputs	PROFIsafe acc. to IEC 61784-3-3
Rated insulation voltage U _i	75 V
Rated impulse withstand voltage U _{imp}	0.5 kV
Shock and vibration resistance	Acc. to EN 60947-5-3
EMC protection requirements	Acc. to EN 61000-4 and DIN EN 61000-6-7
Conformance Class	C
Netload Class	III
Optional features	IRT, MRP, MRPD
Risk times, max. (turn-off times) ³⁾	
Overall system:	200 ms
Fixed value for the processing of safety functions such as	
- Evaluation of submodules with emergency stop, safe pushbuttons or switches, enabling switches, etc.	
- Monitoring of the position of the guard.	
- Monitoring of guard locking.	
Characteristics acc. to EN ISO 13849-1/EN IEC 62061	
Category	4
Safety Integrity Level	SIL 3
Performance Level	PL e
DC	99%
Mission time	20 years
PFH ⁴⁾	5.38 x 10 ⁻⁹

¹⁾ The document *PROFINET Cabling and Interconnection Technology* from the PNO aids in the correct selection of cables.

²⁾ At temperatures < 40 °C, the max. current consumption (bus module including all connected modules/submodules) can be increased to 4 A and the max. feed-in current in the connection block to 16 A.

³⁾ The risk time is the maximum time between the change in an input status and the clearing of the corresponding bit in the bus protocol. See chapter *Calculation example for determining the risk time for safe functions on page 58*.

⁴⁾ Information regarding wearing parts without consideration of fixed failure rates in electronic components.

Calculation example for determining the risk time for safe functions



Important!

The values in this calculation are only examples. Please refer to the operating instructions of the respective device for the values.

Only modules and submodules that contain a safety function flow into the calculation of the risk time. Safe modules and submodules are apparent because they transmit safe bits (PROFIsafe bits) via the bus module to the control system.

Modules with safety functions are, for example:

- Interlocking and locking modules MGB2-I.../MGB2-L...
- Submodules MSM with emergency stop, safe acknowledgment pushbutton, safe selector switch, enabling switch, etc.

The following formula applies to the calculation of the risk time for your system:

$$T_{\text{Risk}} = T_{\text{RiskSystem}} + T_{\text{RiskFunction}}$$

$$T_{\text{RiskSystem}} = T_P + n \times t_L$$

T_{Risk}	= Total risk time of a safety function
T_P	= Processing time for safety function (general figure 200 ms)
t_L	= Latency time for a safe module/submodule (general figure 27 ms)
n	= Number of safe modules/submodules installed in the system
$T_{\text{RiskFunctionSK}}$	= 155 ms
$T_{\text{RiskFunctionUK}}$	= 70 ms
$T_{\text{RiskFunctionElements}}$	= 35 ms (valid for all safe functions except SK and UK)

The following example shows a system with three locking modules. In two of the locking modules, there is one submodule with a safety function installed. There is therefore a total of 5 safe modules/submodules.

System layout	Position	Module/submodule	Safety function?	Processing time T_P	Latency time t_L
	1	Bus module MBM	-	200 ms	-
	2	Locking module MGB2-L	Yes	-	27 ms
	3	Locking module MGB2-L	Yes	-	27 ms
	4	Submodule MSM with emergency stop safety function	Yes	-	27 ms
	5	Interlocking module MGB2-I	Yes	-	27 ms
	6	Submodule MSM	No	-	-
	7	Submodule MSM with emergency stop safety function	Yes	-	27 ms

These data yield the following calculation:

$$T_{\text{RiskSystem}} = 200 \text{ ms} + 5 \times 27 \text{ ms} = 335 \text{ ms}$$

$$T_{\text{RiskSK}} = 335 \text{ ms} + 155 \text{ ms} = 490 \text{ ms}$$

$$T_{\text{RiskUK}} = 335 \text{ ms} + 70 \text{ ms} = 405 \text{ ms}$$

$$T_{\text{RiskElements}} = 335 \text{ ms} + 35 \text{ ms} = 370 \text{ ms}$$

16. Service

If servicing is required, please contact:

EUCHNER GmbH + Co. KG
Kohlhammerstraße 16
70771 Leinfelden-Echterdingen
Germany

Service telephone:

+49 711 7597-500

E-mail:

support@euchner.de

Internet:

www.euchner.com

17. Inspection and service



WARNING

Loss of the safety function because of damage to the device.
In case of damage, the affected module must be replaced completely. Only accessories or spare parts that can be ordered from EUCHNER may be replaced.

Regular inspection of the following is necessary to ensure trouble-free long-term operation:

- › Check the secure mounting of the devices and the connections

Further inspection measures may be necessary for the modules connected and submodules installed. Refer to the related operating instructions.

No servicing is required. Repairs to the device are only allowed to be made by the manufacturer.



NOTICE

The year of manufacture can be seen in the lower right corner of the type label.

18. Declaration of conformity

The product complies with the following requirements:

- › Machinery Directive 2006/42/EC (until January 19, 2027)
- › Machinery Regulation (EU) 2023/1230 (from January 20, 2027)

The EU declaration of conformity can be found at www.euchner.com. Enter the order number of your device in the search box. The document is available under *Downloads*.

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